

Tree Resolution proofs of the Weak Pigeon-Hole Principle

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Abstract

We prove that any optimal tree resolution proof of PHP_n^m is of size $2^{\theta(n \log n)}$, independently from m , even if it is infinity. So far, only a $2^{\Omega(n)}$ lower bound has been known, in the general case. We also show that any, not necessarily optimal, regular tree resolution proof PHP_n^m is bounded by $2^{O(n \log m)}$. To best of our knowledge, this is for the first time, the worst case proof complexity is considered. Finally, we discuss possible connections of our result to Riis' complexity gap theorem for tree resolution.

1 Introduction

Pigeon-Hole Principle (PHP) is probably the simplest and at the same time the most widely used combinatorial principle. In its classical formulations, it states that there is no *injective* map from a finite m -element set to a finite n -element set if $m > n$. PHP_n^m is very intuitive for the human way of thinking, and it is also easily provable within set theory. This is however not the case for some *propositional proof systems*. In his seminal paper [6], Haken showed that any *resolution proof* of PHP_n^{n+1} is of size $2^{\Omega(n)}$. His proof has been simplified and generalised in [16], [4], [2], [1]. For quite a while, the best known result had been a $2^{\Omega(n^2/m)}$ lower bound on any resolution proof of PHP_n^m , thus having left the case $m = \Omega(n^2/\log n)$ as an important open problem in resolution proof complexity. A partial progress had been made in [4], [9], [13], where lower bounds for some *restricted* kind of resolution have been proven. Recently, a $2^{\Omega(n^\epsilon)}$ lower bound on any *regular resolution* proof of PHP_n^m has appeared in [9]. Shortly after that, the problem has finally been solved in [12], where the latter result has been extended to *general, DAG*, resolution.

In the paper, we consider *tree resolution*. Even though it is one of the weakest propositional proof system, studied,

the exact complexity of tree resolution proofs of PHP_n^m has not been known so far. A $2^{\Omega(n)}$ lower bound was shown in [3], whereas one can construct only a $2^{O(n \log n)}$ tree proof by “unfolding” the $2^{O(n)}$ DAG resolution proof given in the same paper. A $2^{O(n \log n)}$ lower bound has been proved in [7], but only for *ordinary* pigeon-hole principle, i.e. PHP_n^{n+1} .

The first contribution (section 3) of our paper is closing the gap. We prove a $2^{\Omega(n \log n)}$ lower bound on any *tree resolution* proof of PHP_n^m , independently from m , even if it is infinity. It is *tight* up to a constant factor in the exponent or, in other words, up to a *polynomial transformation*. As a consequence, we get a super-polynomial separation between DAG and tree resolution. We should however note that much stronger, almost optimal, such separation is known for another kind of tautologies.

The second contribution (section 4) of the paper is considering the *worst-case tree regular resolution* proofs of PHP_n^m . To best of our knowledge, this is for the first time, *the worst case* proof complexity is considered. We prove an *upper bound* of $2^{O(n \log m)}$, which is non-trivial, as there are mn variables, and one can therefore expect the worst case to be as bad as 2^{mn} (we consider of course only proofs which do not contain vacuous weakening of axioms). This has the following very interesting consequence. Consider PHP_n^m , where m is polynomially bounded by n , and denote it by $PHP_n^{\text{poly}(n)}$. The optimal and the worst-case tree regular resolution proofs of $PHP_n^{\text{poly}(n)}$ are *polynomially* related, and so are any two *random* tree regular resolution proofs. This has an interesting consequence for automated theorem proving, as it shows that there are natural problems for which any DLL-proof search heuristic is as good as any other.

Finally (section 5), we discuss some possible refinements of Riis' complexity gap theorem for tree resolution, motivated by our results.

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2 Preliminaries

We first give some definitions. A *literal* is either a propositional variable or the negation of a propositional variable. A *clause* is a set of literals. It is satisfied by a truth assignment if at least one of its literals is true under this assignment. A set of clauses is *satisfiable* if there exists a truth assignment satisfying all the clauses.

As we have already said, by PHP_n^m we denote the claim that there is no *injective map* from a set of size m to a set of size n , where $m > n$. We encode its negation as the following set of clauses

1. $\{p_{i1}, p_{i2}, \dots, p_{in}\}$ for $1 \leq i \leq m$
2. $\{\bar{p}_{ij}, \bar{p}_{ik}\}$ for $1 \leq i \leq m, 1 \leq j < k \leq n$

We allow m to be infinity. In this case, we have an infinite set of clauses, but all the clauses themselves are finite. Although we consider the *injective PHP*, all the results and proofs from the paper remain valid for the *bijective PHP*, too.

Resolution is a proof system designed to *refute* given set of clauses i.e. to prove that it is unsatisfiable. This is done by means of the resolution rule

$$\frac{C_1 \cup \{v\} \quad C_2 \cup \{\bar{v}\}}{C_1 \cup C_2}.$$

Thus, we can derive a new clause from two other clauses that contain a variable and its negation respectively. The goal is to derive the empty clause from the initial ones. Anywhere we say we *prove* some proposition, we mean that first we take its negation in a clausal form and then resolution is used to refute these clauses.

There is an obvious way to represent every resolution refutation as a directed acyclic graph whose nodes are labelled by clauses. The sources, i.e. the vertices with no incoming edges, are the initial clauses. The only sink, i.e. the vertex with no outgoing edges, is the empty clause. Everywhere in the paper, we say “*the size of a proof*”, we really mean *the number of vertices* in the corresponding graph.

We can now define two important restricted versions of resolution. First one is *tree resolution* when the graph is a tree or, in other words, we are not allowed to reuse any previously derived clauses. The other one is *regular resolution* when every variable is resolved at most once along any path from a source to the sink.

For an unsatisfiable set of clause, we can consider the following *search problem*: given a truth assignment, find a clause which is falsified under it. There is a close connection between refuting an unsatisfiable set of clauses by some proof system and solving the corresponding search problem within some model of computation. In [8], it is proven

that tree resolution refutations are equivalent to *boolean decision trees*. More precisely, given a refutation of the set of clauses, it can be viewed as a decision tree, solving the search problem and vice versa. The same result holds for regular resolution refutations and *read-once branching programs*. In contrast to these, general resolution proofs are not equivalent to branching programs. As a matter of fact, there is a polynomial-size branching program, solving the search problem corresponding to PHP_n^{n+1} while all resolution refutations are of exponential size.

Everywhere in the paper, we use the equivalence between a tree resolution proof and a boolean decision tree. All the proofs are, in fact, for decision trees, whereas the results are stated in terms of tree resolution proofs. We only consider tree resolution proofs that are regular. This is not a restriction at all as in a decision tree, it does not make sense to query any variable more than once. On the other hand, if we do not set this restriction, we would not be able to prove any upper bounds, as any given proof can be extended by (unbounded) number of “meaningless” applications of the resolution rule. Thus, from now on, every time we say “tree resolution”, we really mean “tree regular resolution”. As already mentioned we do not allow proofs to contain vacuous weakening of axioms. In terms of decision trees a branch terminates as soon as a contradiction is reached.

A very important technique, we use to prove lower bounds on proofs, is considering a proof as a *Prover-Adversary game*. It is first introduced in [11] and developed further in [10] for general resolution. For tree resolution, it can be simplified, as done in [5]. Adversary claims that there is a satisfying assignment. Prover’s task is to expose him. In order to do that, Prover asks questions about variables according to a decision tree, she holds. Clearly, there is no way for Adversary to win the game. His task is therefore to enforce a big enough subtree, contained in Prover’s decision tree. If he has a strategy, enforcing that, no matter what strategy Prover uses, we have a lower bound on the tree resolution refutations of the given set of clauses.

3 Optimal proofs

We first construct a $2^{O(n \log n)}$ tree resolution proof (in fact, boolean decision tree, as we have already mentioned), and we prove the corresponding lower bound.

Here we fix some notations that we will use in both this and the next section. We denote the bigger, m -element set by M , and the other, n -element set by N . We consider M and N as the two parts of the complete bipartite graph $K_{m,n}$, and then there is 1-1 correspondence between the edges of the graph and variables p . Thus we can speak about a partial matching in $K_{m,n}$ instead of a partial function from M to N . All the queries/questions, from the decision tree, are about the edges. We can however say that a question is

about a vertex, too if the corresponding edge is incident to that vertex.

Upper bound

The sketch of the construction is as follows. Obviously, Prover can restrict herself to the first $n + 1$ elements of M . She asks consecutively all the questions about the first element from M , namely $p_{11}, p_{12}, \dots, p_{1n}$. If all the answers are “no”, a contradiction is found. Otherwise, suppose p_{1j} is the first question with a positive answer. Prover then asks all the remaining questions about the j -th element of N , namely $p_{2j}, p_{3j}, \dots, p_{n+1, n}$. If at least one answer is “yes”, a contradiction is found. If not, we can safely remove the first element from M and the j -th element from N , and then look for a contradiction on a PHP_{n-1}^{m-1} instance.

The boolean decision tree is given on the figure 1 below. The internal nodes are labelled with the queried variables,

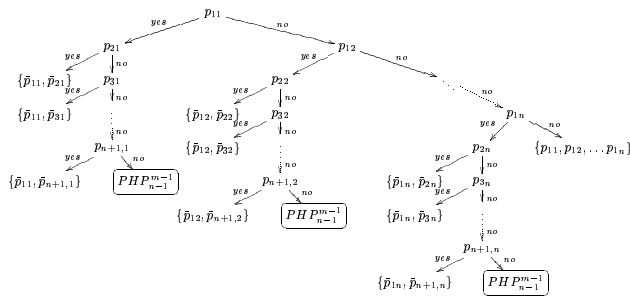


Figure 1. An optimal decision tree for PHP_n^m

and the edges are marked with the corresponding answer. Every external node (leaf) is labelled by the found contradiction, i.e. a clause falsified under the (partial) truth assignment corresponding to the path from the root to this node. The nodes marked by PHP_{n-1}^{m-1} are, in fact, subtrees.

What remains is to estimate the size. The decision tree for PHP_n^m consists of n copies of the decision tree for PHP_{n-1}^{m-1} plus a quadratic in n overhead. More precisely

$$S(n) = \begin{cases} nS(n-1) + 2n^2 + n + 1 & \text{if } n > 1 \\ 5 & \text{if } n = 1 \end{cases},$$

where $S(n)$ is the size of the decision tree for PHP_n^m .

It is now easy to prove by induction that $S(n) \leq 6(n+1)!$. Finally, an application of Stirling's approximation of the factorial gives the desired upper bound.

Lower Bound

The main idea in our proof is to define a function on the nodes of the decision tree. The value of the function at any node should be a lower bound of the size of the subtree

rooted by that node. After having done that, it suffices to compute the function value on the root. The result is a lower bound on the size of any decision tree, solving the search problem for PHP_n^m .

We assume, w.l.o.g., that n is even. W.l.o.g. we can also assume that Prover's decision tree is *read-once*, i.e. along every path any question is asked at most once. Now, we can explain Adversary's strategy.

An important concept, we introduce here, are *counters*. A counter is attached to every vertex in M which is not matched yet to any vertex in N . In addition, there is one special counter that will be explained later on. Initially all the counters are set to zero. During the game, every counter is an upper bound of the number of vertices in N that are “forbidden” for the corresponding vertex in M . When some counter reaches the value n , Adversary “gives up”, although it might be possible to continue the game a few more rounds.

We can now classify all the questions that can appear in the decision tree and show how to maintain the counters. Let k be the size of the partial matching obtained so far, i.e. the number of “yes” answers along the path from the root to the current node. There are three kinds of queries:

1. *Free-choice*. Neither of the two vertices involved is in the current partial matching and the counter of the vertex from M is less than $\frac{n}{2} + k$. Adversary chooses either “yes” or “no” answer with some probability. The actual probability does not matter, the important point is that the free choice forces Prover to branch the decision tree at that point. If the answer is “no”, only the counter of the element from M increases by one. If the answer is “yes” this counter is cancelled, i.e. not maintained any more, but the counters of all the other elements in M are increased by one.
2. *Critical*. Neither of the two vertices involved is in the current partial matching but the counter of the vertex from M is equal to $\frac{n}{2} + k$. Adversary answers “yes”, he current counter is cancelled, and the counters of all the other elements in M are increased by one.
3. *Forced*. Some of the vertices involved (or both) is already in the matching. Adversary answers “no” and does not change any of the counters attached to the elements in M . He however increases by one the special counter, which counts the forced questions.

First of all, it is easy to see that for a given element in M , its counter is an upper bound on the number of elements in N that cannot be matched to that element. There are also some other simple observations to be made. First one says that Adversary always “survives” certain number of rounds.

Lemma 1 *A contradiction can be found only when some counter reaches the value n . In this case, at least $\frac{n}{2}$ “yes” answers must be present on the path from the root to the current node.*

Proof A simple induction on k proves the following assertion: All the counters are bounded from above by $\frac{n}{2} + k$ along any path from a node, where the partial matching is of size k , to the node, where that size becomes $k + 1$. The lemma then follows. \square

The next lemma shows that there must be a very long branch in any decision tree. Together with the main result, it implies that every such tree is unbalanced.

Lemma 2 *In every decision tree for PHP_n^m , there is a path of length $\Omega(n^2)$.*

Proof Consider the path, where Adversary answers “no” to every free-choice question. It is now easy to observe that when k -th critical questions asked, the corresponding vertex from M has a counter value equal to $\frac{n}{2} + k - 1$. That counter has been increased $k - 1$ times because of the previous $k - 1$ critical question. The remaining $\frac{n}{2}$ increases are result of “no” answers to free-choice question about the corresponding vertex. Thus, along the particular path, we consider, any “yes” answer is preceded by $\frac{n}{2}$ negative answers about the same vertex.

The lemma 1 claims that every path contains at least $\frac{n}{2}$ “yes” answers. Therefore our path contains at least $\frac{n^2}{4}$ “no” answers. \square

We can now prove the main result.

Theorem 1 *Every tree resolution proof of PHP_n^m is of size $2^{\Omega(n \log n)}$.*

Proof First we define an appropriate function as it has been explained in the beginning of the section.

Let us denote by k the size of the partial matching at the current node u , i.e. the number of “yes” answers along the path from the root to u . Let us also sort the $m - k$ unmatched vertices from M in decreasing order of their counters, and denote the values of the counters themselves by $p_1 \geq p_2 \geq \dots \geq p_{m-k}$. The forced question counter is denoted by p_0 . The value of the function at the node is then defined by

$$f(u) = \prod_{i=1}^{\frac{n}{2}-k} q_i,$$

$$\text{where } q_i = \begin{cases} \frac{n}{2} + k - i - p_i & \text{if it is positive} \\ 1 & \text{elsewhere} \end{cases}$$

On the root, r , we have $f(r) = (\frac{n}{2} - 1)!$, so that $f(r) = 2^{\Omega(n \log n)}$. It only remains to prove that at any node the

function value is a lower bound for the size of the subtree rooted by the node.

The proof is by induction on the tuples of the form

$$\left(p_1, p_2, \dots, p_{\frac{n}{2}-k}, p_0 + \sum_{i=\frac{n}{2}-k+1}^{m-k} p_i \right).$$

We order them as follows. The shorter a tuple, the smaller it is. If two tuples have equal length, the lexicographically *bigger* one is the smaller. Clearly, this ordering makes the induction work from the leaves to the root of the decision tree, as the tuple on any node is strictly bigger than the tuples on its successors in the tree.

The basis case is then $k = \frac{n}{2}$, where $f(u) = 1$, as the product is empty. Obviously, the function value at the node is a lower bound of the corresponding subtree, no matter what the only element of the tuple is.

To prove the induction step, we need to consider all possible kind of questions that can appear at the current node u .

1. **Forced.** We consider the “no” branch only. Denoting its root (the “no” successor of u) by v , we have $f(u) = f(v)$, as only p_0 increases by one when going from u to v and f does not depend from p_0 . By the induction hypothesis, we are done.
2. **Critical.** W.l.o.g. we assume that the question is about the element, having p_1 as a counter. It is so, because a critical question always involves the biggest counter (Even if there are many counters with the biggest value $\frac{n}{2} + k$, we can always consider p_1 , as two elements, having the same counter value are indistinguishable to Adversary’s strategy). We consider the “yes” branch only. Denoting the “yes” successor of u by v , we have again $f(u) = f(v)$. That is the case, because all the counters $p_2, \dots, p_{\frac{n}{2}-k}$ increase by one when going from u to v , but so does k , therefore the contributions $q_2, \dots, q_{\frac{n}{2}-k}$ do not change. q_1 vanishes at v , but its value at u is one, as $p_1 = \frac{n}{2} + k$. By the induction hypothesis, we are done.
3. **Free-choice.** There are three sub-cases:
 - (a) The index involved, j , is greater than $\frac{n}{2} - k$. W.l.o.g. we can also assume $p_{\frac{n}{2}-k} > p_j$ since if they were equal Adversary could behave as the question were about $\frac{n}{2} - k$ -th element (again, any two vertices having the same counter value are indistinguishable to Adversary’s strategy). The “no” answer then does not change anything except the last element of the tuple, but f does not depend on it. So, $f(u) = f(v)$, where v is the “no” successor of u . By the induction hypothesis, we are done.

- (b) The index involved, j , is between 1 and $\frac{n}{2} - k$, but the contribution, q_j , of that element to the function f is one. That is similar to the previous sub-case, as the “no” answer leaves the value of f unchanged when going from u to its “no” successor v .
- (c) The index j is between 1 and $\frac{n}{2} - k$ and the contribution, q_j , of that element to the function f is greater than one. This is the only non-trivial case, in the sense that we need consider both subtrees of the current node u . Note that if there are many counters, having the same value equal to p_j , w.l.o.g. we can think that j is the minimum such index, so that the “no” answer does not change the order of the counters.

The “no” subtree gives the tuple

$$\left(p_1, \dots, p_{j-1}, p_j + 1, p_{j+1}, \dots, p_{\frac{n}{2}-k}, p_0 + \sum_{i=\frac{n}{2}-k+1}^{m-k} p_i \right)$$

and the value

$$f(v) = (q_j - 1) \prod_{\substack{i=1 \\ i \neq j}}^{\frac{n}{2}-k} q_i.$$

The “yes” subtree gives

$$\left(p_1 + 1, \dots, p_{j-1} + 1, p_{j+1} + 1, \dots, p_{\frac{n}{2}-k} + 1, m - \frac{n}{2} + p_0 + \sum_{i=\frac{n}{2}-k+1}^{m-k} p_i \right)$$

and the value

$$f(w) = \prod_{\substack{i=1 \\ i \neq j}}^{\frac{n}{2}-k} q_i.$$

The induction hypothesis then applies to both subtrees, so the size of the current subtree is at least

$$1 + f(v) + f(w) = 1 + f(u) > f(u).$$

This completes the proof. \square

4 Worst case proofs

We first construct a $2^{O(n \log m)}$ boolean decision tree for PHP_n^m which is a lower bound for the worst-case regular

tree resolution proofs. We also show the same upper bound, i.e. any such proof cannot be worse than that. It is very important to now note that “worst case”, in our context, has a *completely different meaning* than the usual one, used in Complexity Theory or Analysis of Algorithms.

Lower bound

The sketch of the construction is as follows. Prover ask all the questions about the first element from N , namely $p_{11}, p_{21}, \dots, p_{m1}$. If all the answers are “no”, we can remove the first element from N , and thus get an PHP_{n-1}^m instance. Otherwise, suppose p_{i1} is the first question with a positive answer. Prover then asks all the remaining questions about the first element of N , namely $p_{i+11}, p_{i+21}, \dots, p_{m1}$. If at least one answer is “yes”, a contradiction is found. If not, we can safely remove the first element from N and the i -th element from M , and then look for a contradiction on a PHP_{n-1}^{m-1} instance.

The boolean decision tree is given on the figure 2 below.

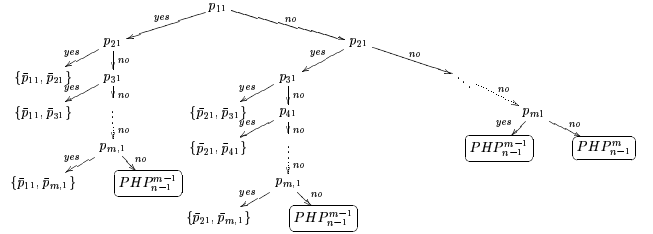


Figure 2. A worst-case decision tree for PHP_n^m

What remains is to estimate the size. The decision tree for PHP_n^m consists of m copies of the decision tree for PHP_{n-1}^m , one decision tree for PHP_{n-1}^m plus a quadratic in m overhead. More precisely

$$S(m, n) = \begin{cases} mS(m-1, n-1) + 5 & \text{if } n > 1 \\ S(m, n-1) + m^2 & \text{if } n = 1 \end{cases},$$

where $S(m, n)$ denotes the size of the decision tree for PHP_n^m .

We have

$$\begin{aligned} S(m, n) &> mS(m-1, n-1) \\ &> m(m-1)S(m-2, n-2) \\ &> \dots \prod_{i=0}^{\lceil \frac{n}{2} \rceil - 1} (m-i) S\left(m - \left\lceil \frac{n}{2} \right\rceil, \left\lfloor \frac{n}{2} \right\rfloor\right). \end{aligned}$$

Therefore, for every $m > n > 2$, we get

$$S(m, n) > 5 \left(m - \left\lceil \frac{n}{2} \right\rceil \right)^{\lceil \frac{n}{2} \rceil} = 2^{\Omega(n \log m)}.$$

Upper bound

The main idea is the same as in the proof of the lower bound on the optimal refutation. This time however, we introduce the counters to the elements of the set N . Every counter p_j equals to m minus the number of questions about the j -th element of N that have already been asked. In other words, the counter contains *exactly* the number of possible questions about the element to be asked in the future. There is also one global counter p_0 that is the sum of all the counters p_j , $1 \leq j \leq n$.

We can now prove the main result of this section.

Theorem 2 *Every regular tree resolution proof of PHP_n^m is of size $2^{O(n \log m)}$.*

Proof Again we define an appropriate function on the nodes of the read-once decision tree. At any node the value of the function will be an upper bound on the size of the subtree rooted at that node.

Let us denote by u the current node, and by P , $P \subseteq N$, the set of all the vertices from N that are not yet matched to any vertex in M . The function f is defined as

$$f(u) = 2(p_0 + 1) \prod_{j \in P} (p_j + 1) - 1.$$

On the root of the tree, r , we have $f(r) = 2(mn + 1)(m + 1)^n - 1$, so that $f(r) = 2^{O(n \log m)}$. It only remains to prove that at any node the function value is an upper bound for the size of the subtree rooted by the node.

The proof is by induction on the global counter p_0 .

The basis case is then $p_0 = 0$, so that all other p 's are zeros and therefore $f(u) = 1$. In this case all variables have already been queried, as there are no possible questions left. Therefore a contradiction has already been found and $f(u)$ is an upper bound.

To prove the induction step, we consider the following two cases.

1. The question at the current node, u , is about the i -th element from N , and $i \notin P$. This means that element has already been matched to some element in M , so that the current question is forced. Therefore, the “yes” subtree consists of a single vertex, labelled by the contradiction found. Let us denote by v the “no” successor of u . The induction hypothesis applies at v , as p_0 decreases by one there, so the size of any subtree rooted at u is at most

$$\begin{aligned} 2 + f(v) &= 2 + 2p_0 \prod_{j \in P} (p_j + 1) - 1 \\ &\leq 2(p_0 + 1) \prod_{j \in P} (p_j + 1) - 1 \\ &= f(u). \end{aligned}$$

2. The question at the current node, u , is about the i -th element from N , and $i \in P$. The induction hypothesis then applies to both “yes” and “no” successors of u . Denoting them by v and w respectively, we have that the size of any subtree rooted at u is at most

$$\begin{aligned} 1 + f(v) + f(w) &= 1 + 2p_0 \prod_{j \in P \setminus \{i\}} (p_j + 1) - 1 + \\ &\quad 2p_0 p_i \prod_{j \in P \setminus \{i\}} (p_j + 1) - 1 \\ &= 2p_0 \prod_{j \in P} (p_j + 1) - 1 \\ &< 2(p_0 + 1) \prod_{j \in P} (p_j + 1) - 1 \\ &= f(u). \end{aligned}$$

This completes the proof. \square

5 Link to Complexity Gap theorem

In this section, we discuss possible refinements and extensions of Riis’ complexity gap theorem for tree resolution. They are motivated by our results presented in the previous two sections.

We first need to state the complexity gap theorem itself. We give here a slightly different version than the one from the original paper [14]

We are given a first order sentence ψ of predicate logic that fails in all finite models. There is a procedure which translates the sequence of sentences $A_n := \psi$ has no models of size n'' into an unsatisfiable set $C_{\psi, n}$ of clauses. The sequence $C_{\psi, n}$ is uniformly generated (in the sense of [15]) and its size is bound by a polynomial in n . The complexity gap theorem states that either 1 or 2 holds:

1. The sequence $C_{\psi, n}$ have polynomial size in n tree resolution refutations.
2. There exists $\lambda > 0$ such that each tree resolution refutation of $C_{\psi, n}$ must contain at least $2^{\lambda n}$ clauses.

Furthermore 2 holds if and only if ψ has an infinite model.

So, the gap is between polynomial and exponential size proofs and shows that no super-polynomial (e.g. $2^{\theta(\log^p n)}$ for some $p > 1$) and sub-exponential (e.g. $2^{\theta(n^\varepsilon)}$ for some $0 < \varepsilon < 1$) optimal proofs can appear.

We will concentrate on the sentences falling in the second case, i.e. requiring exponential size tree resolution refutations. Let us denote the class of all such sentences by *Exp*.

Let us first consider the following encoding of PHP_n^{n+1} as a first order sentence (given also in [14])

$$(\forall x, y (x = y) \vee (f(x) \neq f(y))) \wedge (\exists c \forall x f(x) \neq c).$$

The complexity gap theorem gives only a $2^{\Omega(n)}$ lower bound, whereas we have shown that its real complexity is $2^{\theta(n \log n)}$. Going further, let us encode $PHP_{n^q}^{n^p}$, where $p, q \in \mathbb{Z}_+$ and $p > q$, as a first order sentence

$$\forall \vec{x}, \vec{y} (\vec{x} = \vec{y}) \vee (\vec{F}(\vec{x}) \neq \vec{F}(\vec{y})).$$

Here $\vec{x} = (x_1, x_2, \dots, x_p)$ and $\vec{F}(\vec{x}) = (f_1(\vec{x}), f_2(\vec{x}), \dots, f_q(\vec{x}))$. Our result shows that the exact complexity is $2^{\theta(n^q \log n)}$ for any arbitrary tree regular resolution proof.

On the other hand, let us consider the *minimum element principle*, saying that if R is a total order, it has a minimal element. Its negation can be encoded as

$$\begin{aligned} & (\forall x, y (x \neq y) \rightarrow (R(x, y) \oplus R(y, x))) \wedge \\ & (\forall x, y, z (R(x, y) \wedge R(y, z)) \rightarrow R(x, z)) \wedge \\ & (\forall x \exists y R(y, x)). \end{aligned}$$

Here $R(x, y)$ stands for $x < y$. It can easily be proven that the optimal tree resolution proofs of it are of size $2^{\theta(n)}$, whereas the worst-case proofs are of size $2^{\theta(n^2)}$. Clearly, if we replace the singletons by p -tuples, the corresponding optimal and worst-case proofs are $2^{\theta(n^p)}$ and $2^{\theta(n^{2p})}$ respectively.

Let us now denote by $Size(t(n))$ the class of first order sentences of propositional logic that have their *optimal tree resolution proofs* of size $t(n)$, and by Opt - the class for which any arbitrary tree regular resolution proof is *polynomially* related to the *optimal* one.

To summarise, our two examples show

1. The classes $Size(2^{\theta(n^p)})$, $p \in \mathbb{Z}_+$ and $Size(2^{\theta(n^q \log n)})$, $q \in \mathbb{Z}_+$ are nonempty.
2. The classes $Opt \cap Size(2^{\theta(n^q \log n)})$, $q \in \mathbb{Z}_+$ and $Size(2^{\theta(n^p)}) \setminus Opt$, $p \in \mathbb{Z}_+$ are nonempty.

At the same time, the following three interesting open questions arise

1. Is it the case that $Exp = \bigcup_{p \in \mathbb{Z}_+} Size(2^{\theta(n^p)}) \cup \bigcup_{q \in \mathbb{Z}_+} Size(2^{\theta(n^q \log n)})$? That is to ask whether the exponential side of Complexity-Gap Theorem can be further refined, so that each complexity subclass inside it is either $Size(2^{\theta(n^p)})$ or $Size(2^{\theta(n^q \log n)})$ for some positive integer p/q .
2. Is it the case that $Opt \subseteq \bigcup_{q \in \mathbb{Z}_+} Size(2^{\theta(n^q \log n)})$? That is to ask whether all trivially automatisable problems belong to this particular family of optimal-proof-size classes. Alternatively (and equivalently, assuming

a positive answer to the previous question), we can ask whether $Opt \cap Size(2^{\theta(n^p)}) = \emptyset$ for every positive integer p .

3. Is it the case that if $s \in Size(2^{\theta(n^p)})$ for some $p \in \mathbb{Z}_+$, the worst-case complexity of the s is at least $2^{\theta(n^{2p})}$?

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