Hyper-heuristics Tutorial

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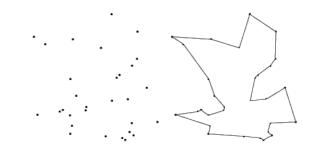
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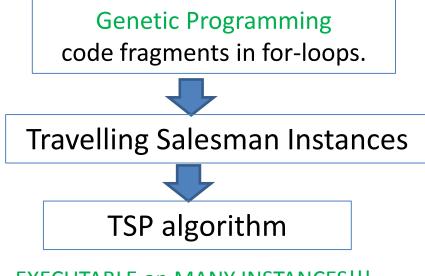
8 May, 2015

John's perspective of hyperheuristics

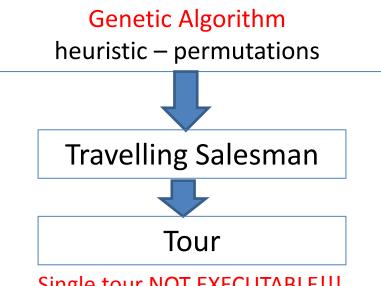
Conceptual Overview

Combinatorial problem e.g. Travelling Salesman Exhaustive search ->heuristic?





EXECUTABLE on MANY INSTANCES!!!

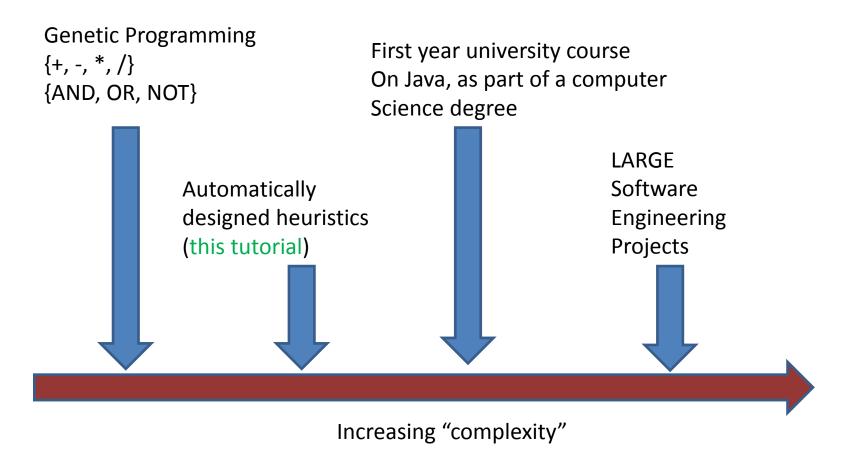


Single tour NOT EXECUTABLE!!!

Give a man a fish and he will eat for a day. Teach a man to fish and he will eat for a lifetime. Scalable? General?

John R. Woodward, Daniel R. TNiew domains for GP 3

Program Spectrum



Plan: From Evolution to Automatic Design

- 1. Evolution, Genetic Algorithms and Genetic Programming
- 2. Motivations (conceptual and theoretical)
- 3. Examples of Automatic Generation:
 - Evolutionary Algorithms (selection, mutation, crossover)
 - Black Box Search Algorithms
 - Bin packing
 - Evolutionary Programming
- 4. Visualization
- 5. Step-by-step guide
- 6. Wrap up (comparison, history, conclusions, summary, etc.)
- 7. Questions (during AND after...), please! 😳

Now is a good time to say you are in the wrong room $\ensuremath{\mathfrak{S}}$

Evolution GA/GP

- Generate and test: cars, code, models, proofs, medicine, hypothesis.
- Evolution (select, vary, inherit).
- Fit for purpose

Feedback loon

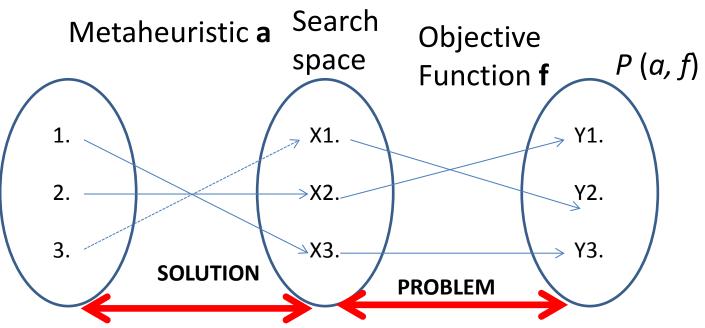
Inheritance **Off-spring** have similar Genotype (phenotype) PERFECT **CODE** [3]





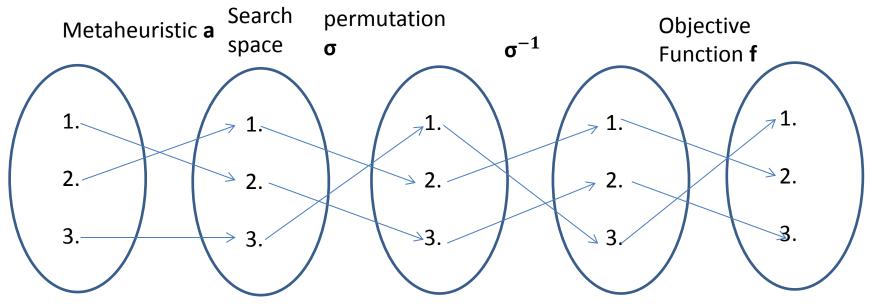


Theoretical Motivation 1



- 1. A **search space** contains the <u>set of all possible solutions</u>.
- 2. An **objective function** determines the <u>quality of solution</u>.
- 3. A (Mathematical idealized) metaheuristic determines the <u>sampling order (i.e. enumerates i.e. without replacement)</u>. It is a (approximate) permutation. What are we learning?
- 4. Performance measure *P* (*a*, *f*) depend only on y1, y2, y3
- 5. <u>Aim find a solution with a near-optimal objective value using a</u> Metaheuristic <u>ANY QUESTIONS BEFORE NEXT SLIDE</u>?

Theoretical Motivation 2



 $P(a, f) = P(a \sigma, \sigma^{-1} f) \qquad P(A, F) = P(A\sigma, \sigma^{-1} F) \text{ (i.e. permute bins)}$ P is a **performance measure**, (based only on output values). σ, σ^{-1} are a permutation and inverse permutation. A and F are probability distributions over algorithms and functions). F is a problem class. ASSUMPTIONS IMPLICATIONS 1. Metaheuristic a applied to function $\sigma\sigma^{-1}f$ (that is f)

2. Metaheuristic $\mathbf{a}\sigma$ applied to function $\sigma^{-1}f$ precisely identical.

Theoretical Motivation 3 [1,14]

- The base-level learns about the function.
- The meta-level learn about the distribution of functions
- The sets do not need to be finite (with infinite sets, a uniform distribution is not possible)
- The functions do not need to be computable.
- We can make claims about the Kolmogorov Complexity of the functions and search algorithms.
- p(f) (the probability of sampling a function) is all we can learn in a black-box approach.

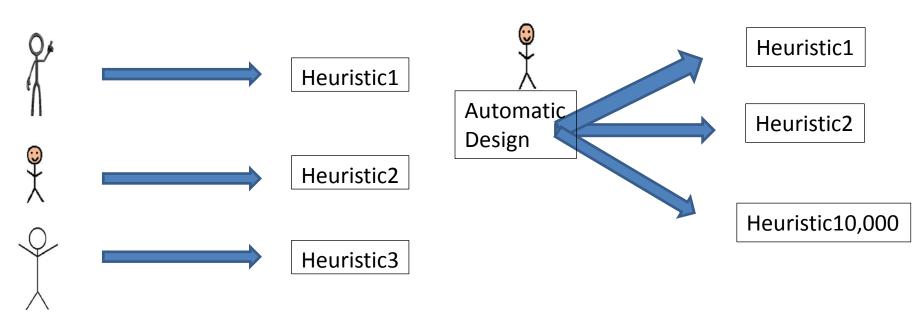
One Man – One/Many Algorithm

- 1. Researchers design heuristics by hand and test them on problem instances or arbitrary benchmarks off internet.
- 2. Presenting results at conferences and publishing in journals. In this talk/paper we propose a new algorithm...

1. Challenge is defining an algorithmic framework (**set**) that **includes** useful algorithms. **Black art**

2. Let Genetic Programming <u>select the</u> <u>best algorithm for the problem class at</u> <u>hand</u>. Context!!! Let the data speak for itself without imposing our assumptions.

In this talk/paper we propose a 10,000 algorithms...



Daniel's perspective of hyperheuristics

Real-World Challenges

- Researchers strive to make algorithms increasingly general-purpose
- But practitioners have very specific needs
- Designing custom algorithms tuned to particular problem instance distributions and/or computational architectures can be very time consuming

Automated Design of Algorithms

- Addresses the need for custom algorithms
- But due to high computational complexity, only feasible for repeated problem solving
- Hyper-heuristics accomplish automated design of algorithms by searching program space

Hyper-heuristics

- Hyper-heuristics are a special type of meta-heuristic
 - Step 1: Extract algorithmic primitives from existing algorithms
 - Step 2: Search the space of programs defined by the extracted primitives
- While Genetic Programming (GP) is particularly well suited for executing Step 2, other meta-heuristics can be, and have been, employed
- The type of GP employed matters [24]

Case Study 1: The Automated Design of Selection Heuristics

Evolving Selection Heuristics [16]

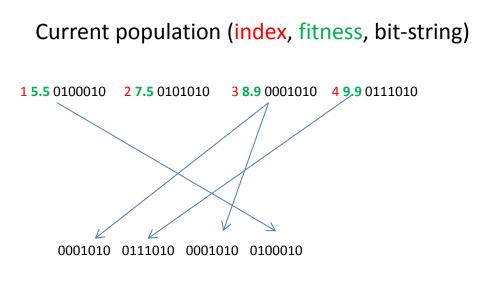
• Rank selection

P(i) α *i*

Probability of selection is proportional to the **index** in sorted population

Fitness Proportional
 P(i) α fitness(i)

Probability of selection is proportional to the **fitness** *Fitter individuals are more likely to be selected in both cases.*

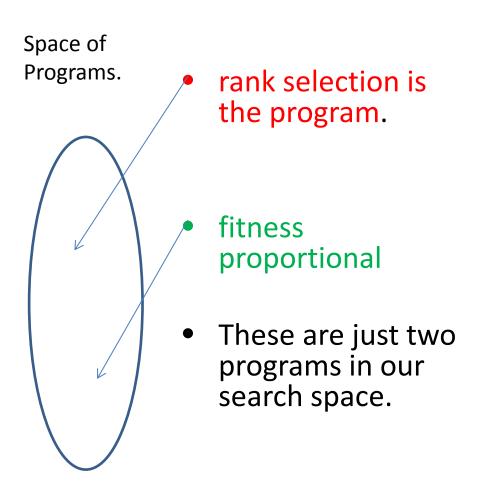


Next generation

Framework for Selection Heuristics

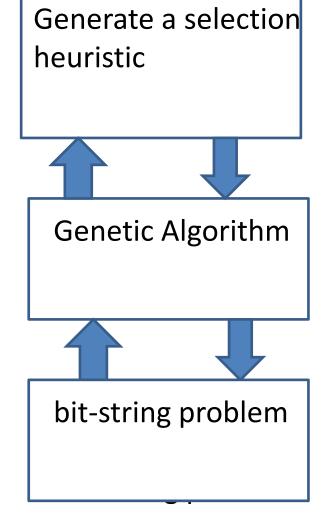
Selection heuristics operate in the following framework for all individuals p in population select p in proportion to value(p);

- To perform rank selection replace value with index i.
- To perform fitness proportional selection replace value with fitness



Selection Heuristic Evaluation

- Selection heuristics are generated by random search in the top layer.
- heuristics are used as for selection in a GA on a bit-string problem class.
- A value is passed to the upper layer informing it of how well the function performed as a selection heuristic.



Generate and test X2

Program space of selection heuristics

Framework for selection heuristics. Selection function plugs into a Genetic Algorithm

Problem class: A probability distribution Over bit-string problems

Experiments for Selection

- Train on 50 problem instances (i.e. we run a single selection heuristic for 50 runs of a genetic algorithm on a problem instance from our problem class).
- The training times are ignored
 - we are not comparing our generation method.
 - we are comparing our selection heuristic with rank and fitness proportional selection.
- Selection heuristics are tested on a second set of 50 problem instances drawn from the same problem class.

Problem Classes

- 1. A problem class is a probability distribution of problem instances.
- 2. Generate values N(0,1) in interval [-1,1] (if we fall outside this range we regenerate)
- 3. Interpolate values in range [0, 2^{num-bits}-1]
- 4. Target bit string given by Gray coding of interpolated value.
- The above 3 steps generate a distribution of target bit strings which are used for hamming distance problem instances. "shifted ones-max"

Results for Selection Heuristics

	Fitness Proportional	Rank	generated-selector	
mean	0.831528	0.907809	0.916088	
std dev	0.003095	0.002517	0.006958	
min	0.824375	0.902813	0.9025	
max	0.838438	0.914688	0.929063	

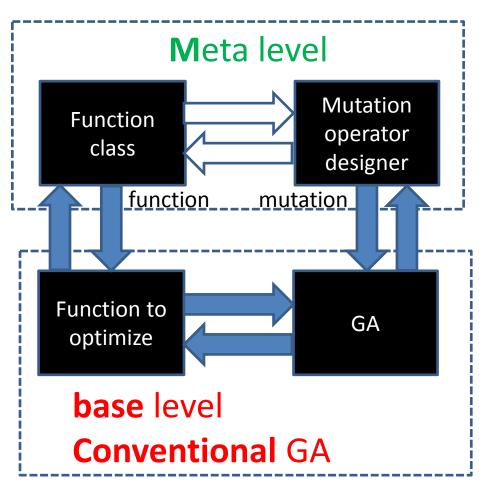
Performing t-test comparisons of fitnessproportional selection and rank selection against generated heuristics resulted in a p-value of better than 10⁻¹⁵ in both cases. In both of these cases the generated heuristics outperform the standard selection operators (rank and fit-proportional).

Take Home Points

- automatically designing selection heuristics.
- We should design heuristics for problem classes i.e. with a context/niche/setting.
- This approach is human-competitive (and human cooperative).
- Meta-bias is necessary if we are to tackle multiple problem instances.
- Think frameworks not individual algorithms we don't want to solve problem instances we want to solve classes (i.e. many instances from the class)!

Meta and Base Learning [15]

- At the base level we are learning about a specific function.
- 2. At the **meta** level we are learning about the probability distribution.
- We are just doing "generate and test" on "generate and test"
- 4. What is being passed with each **blue arrow**?
- 5. Training/Testing and Validation 8 May, 2015



Compare Signatures (Input-Output)

Genetic Algorithm

• $(B^n \rightarrow R) \rightarrow B^n$

Input is an objective function mapping bitstrings of length n to a real-value.

Output is a (near optimal) bit-string

i.e. the <u>solution</u> to the problem <u>instance</u>

Genetic Algorithm FACTORY

• $[(B^n \rightarrow R)] \rightarrow$ $((B^n \rightarrow R) \rightarrow B^n)$

Input is a *list of* functions mapping bit-strings of length n to a realvalue (i.e. sample problem instances from the problem class).

Output is a (near optimal) mutation operator for a GA

i.e. the <u>solution method</u> (algorithm) to the <u>problem</u> <u>class</u>

We are raising the level of generality at which we operate.

Case Study 2: The Automated Design of Crossover Operators [20]

Motivation

• Performance Sensitive to Crossover Selection

 Identifying & Configuring Best Traditional Crossover is Time Consuming

- Existing Operators May Be Suboptimal
- Optimal Operator May Change During Evolution

Some Possible Solutions

• Meta-EA

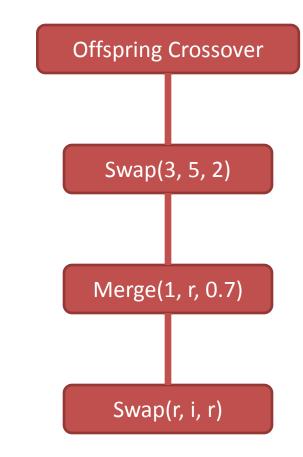
Exceptionally time consuming

Self-Adaptive Algorithm Selection

 Limited by algorithms it can choose from

Self-Configuring Crossover (SCX)

- Each Individual Encodes a Crossover Operator
- Crossovers Encoded as a List of Primitives
 - Swap
 - Merge
- Each Primitive has three parameters
 - Number, Random, or Inline



Applying an SCX

Concatenate Genes



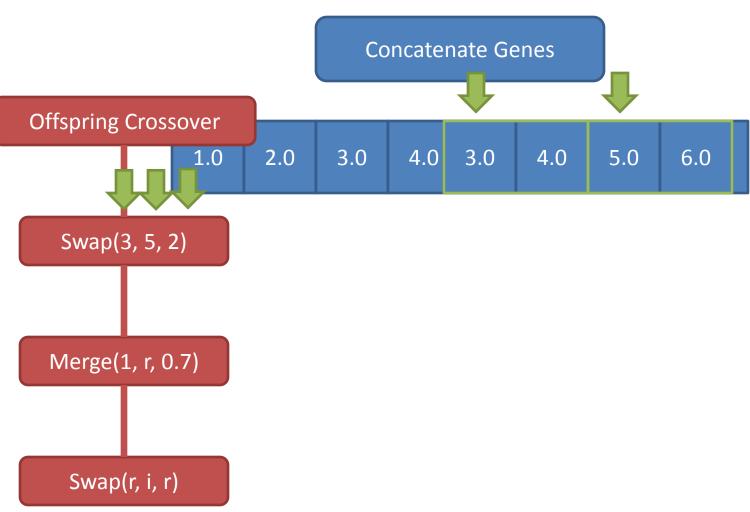
The Swap Primitive

- Each Primitive has a type
 - Swap represents crossovers that move genetic material



- First Two Parameters
 - Start Position
 - End Position
- Third Parameter Primitive Dependent
 - Swaps use "Width"

Applying an SCX



The Merge Primitive

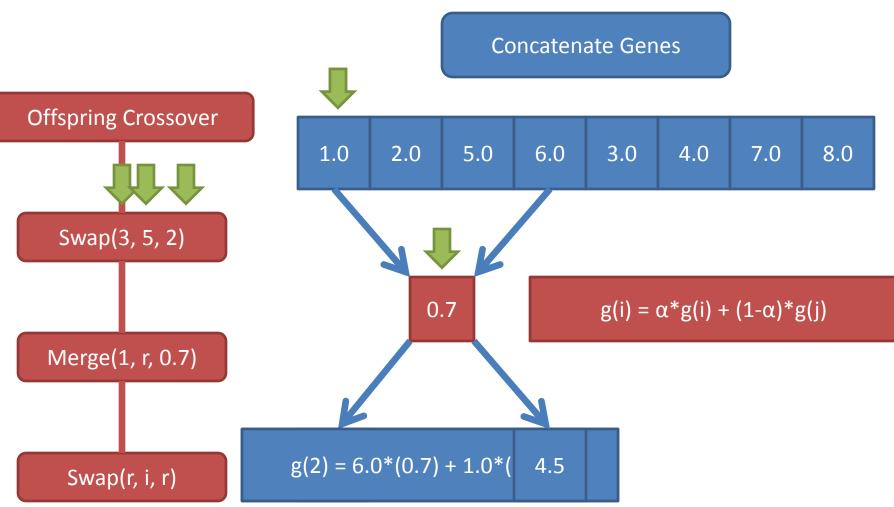
• Third Parameter Primitive Dependent

- Merges use "Weight"



- Random Construct
 - All past primitive parameters used the Number construct
 - "r" marks a primitive using the Random Construct
 - Allows primitives to act stochastically

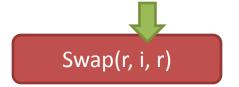
Applying an SCX



The Inline Construct

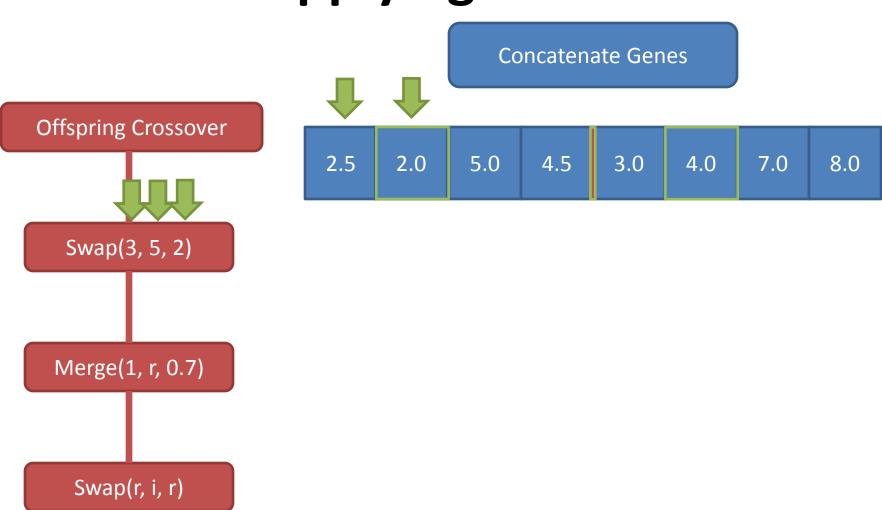
• Only Usable by First Two Parameters

• Denoted as "i"



 Forces Primitive to Act on the Same Loci in Both Parents

Applying an SCX

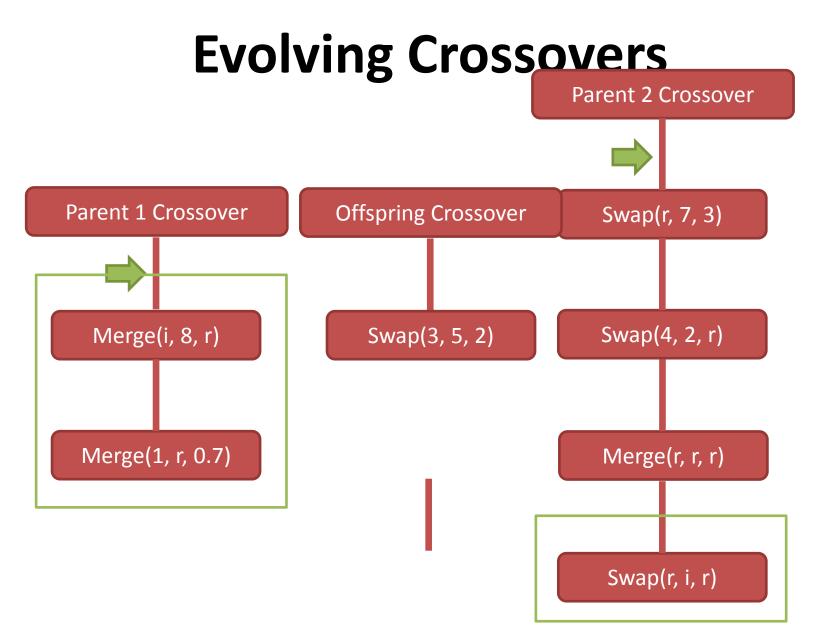


Applying an SCX

Remove Exess Genes

ate Genes

2.5 4.0 5.0 4. Offspring Genes		3.0	2.0	7.0	8.0

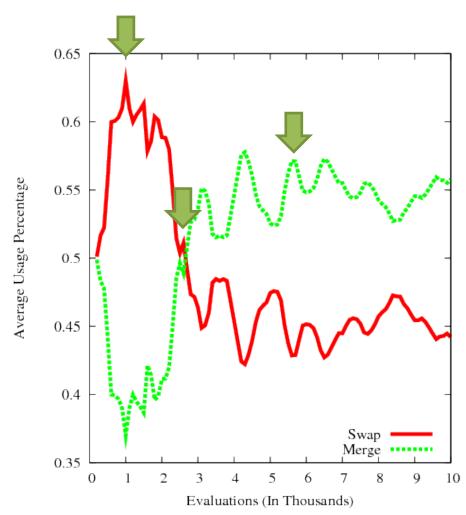


Empirical Quality Assessment

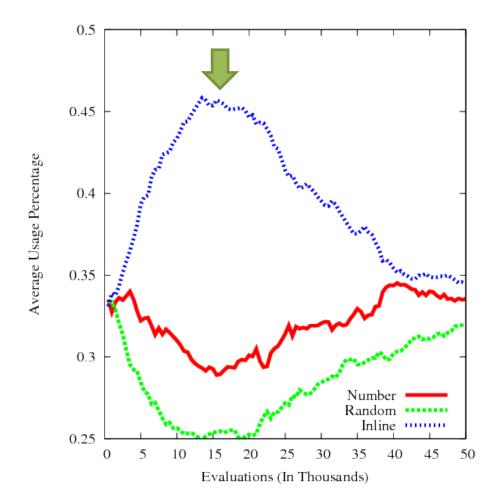
- Compared Against
 - Arithmetic Crossover
 - N-Point Crossover
 - Uniform Crossover
- On Problems
 - Rosenbrock
 - Rastrigin
 - Offset Rastrigin
 - NK-Landscapes
 - DTrap

Problem	Comparison	SCX
Rosenbrock	-86.94 (54.54)	-26.47 (23.33)
Rastrigin	-59.2 (6.998)	-0.0088 (0.021)
Offset Rastrigin	-0.1175 (0.116)	-0.03 (0.028)
NK	0.771 (0.011)	0.8016 (0.013)
DTrap	0.9782 (0.005)	0.9925 (0.021)

Adaptations: Rastrigin



Adaptations: DTrap



SCX Overhead

- Requires No Additional Evaluation
- Adds No Significant Increase in Run Time
 All linear operations
- Adds Initial Crossover Length Parameter
 - Testing showed results fairly insensitive to this parameter
 - Even worst settings tested achieved better results than comparison operators

Conclusions

- Remove Need to Select Crossover Algorithm
- Better Fitness Without Significant Overhead
- Benefits From Dynamically Changing Operator
- Promising Approach for Evolving Crossover Operators for Additional Representations (e.g., Permutations)

Additions to Genetic Programming

1. final program is part human constrained part (forloop) machine generated (body of for-loop).

2. In GP the initial population is **typically randomly created**. Here we (can) initialize the population with **already known good solutions** (which also confirms that we can express the solutions). (improving rather than evolving from scratch) – standing on shoulders of giants. Like genetically modified crops – we start from existing crops.

3. Evolving on **problem classes** (samples of problem instances drawn from a problem class) not instances.

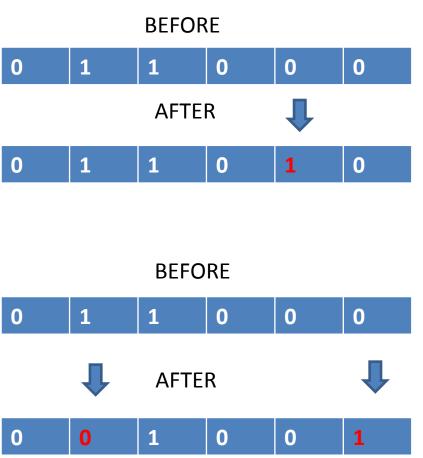
Problem Classes Do Occur

- 1. Problem classes are probability distributions over problem instances.
- 2. Travelling Salesman
 - 1. Distribution of cities over different counties
 - 2. E.g. USA is square, Japan is long and narrow.
- 3. Bin Packing & Knapsack Problem
 - 1. The items are drawn from some probability distribution.
- 4. Problem classes do occur in the real-world
- 5. Next slides demonstrate **problem classes** and **scalability** with on-line bin packing.

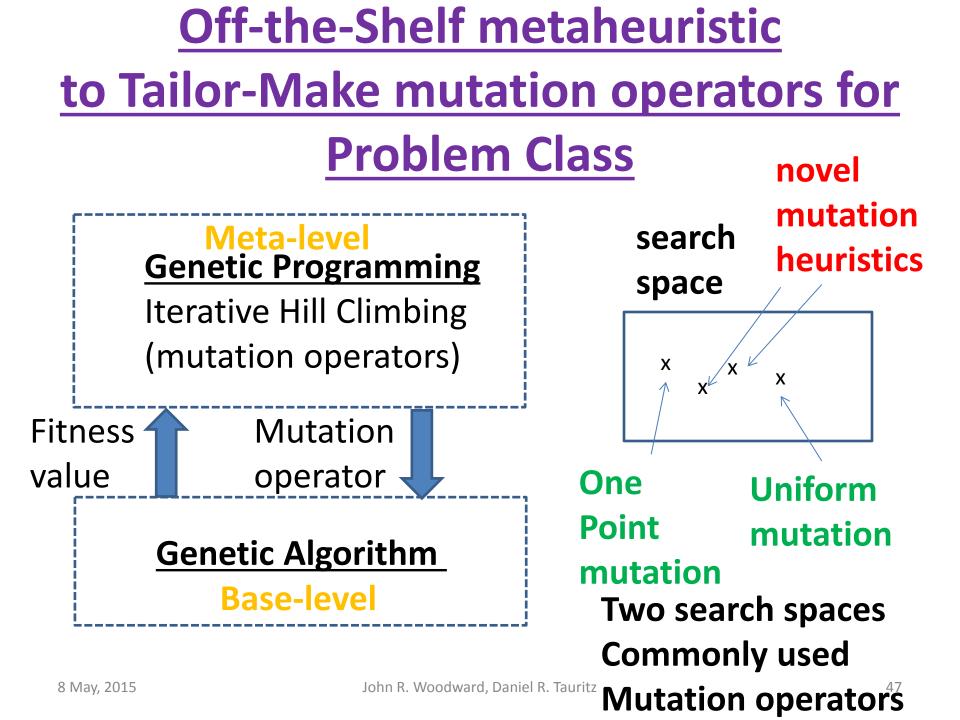
Case Study 3: The Automated Design of Mutation Operators

Two Examples of Mutation Operators

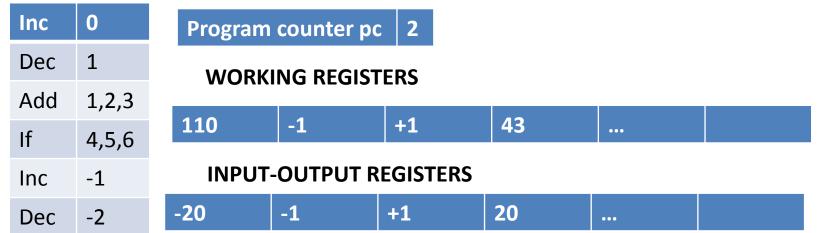
- One point mutation flips ONE single bit in the genome (bit-string).
- (1 point to n point mutation)
- Uniform mutation flips ALL bits with a small probability
 p. No matter how we vary
 p. it will never be one point
 mutation.
- Lets invent some more!!!
- Solved NO, lets build a general method (for problem class)



What probability distribution of problem instances are these intended



Building a Space of Mutation Operators



A program is a list of instructions and arguments.

A **register** is set of addressable memory (R0,..,R4). Negative register addresses means **indirection**. A program can only **affect IO registers indirectly**. **positive (TRUE) negative (FALSE)** on output register.

Insert bit-string on IO register, and extract from IO register

Arithmetic Instructions

These instructions perform arithmetic operations on the registers.

- Add Ri ← Rj + Rk
- Inc Ri ← Ri + 1
- **Dec** Ri ← Ri 1
- Ivt $Ri \leftarrow -1 * Ri$
- **Clr** Ri ← 0
- **Rnd** Ri ← Random([-1, +1]) //mutation rate
- Set Ri ← value
- Nop //no operation or identity 8 May, 2015 John R. Woodward, Daniel R. Tauritz

Control-Flow Instructions

These instructions control flow (NOT ARITHMETIC). They include branching and iterative imperatives.

Note that this set is *not Turing Complete*!

- If if(Ri > Rj) pc = pc + |Rk| why modulus?
- IfRand if(Ri < 100 * random[0,+1]) pc = pc + Rj//allows us to build mutation probabilities WHY?
- **Rpt** Repeat |Ri| times next |Rj| instruction
- **Stp** terminate

Expressing Mutation Operators

•	Line	UNIFORM	ONE POINT	MUTATION
•	0	Rpt, 33, 18	Rpt, 33, 18	 Uniform mutation
•	1	Nop	Nop	
•	2	Nop	Nop	Flips all bits with a
•	3	Nop	Nop	fixed probability.
•	4	Inc, 3	Inc, 3	fixed probability.
•	5	Nop	Nop	4 instructions
•	6	Nop	Nop	• One naint mutation
•	7	Nop	Nop	 One point mutation
•	8	IfRand, 3, 6	IfRand, 3, 6	flips a single bit.
•	9	Nop	Nop	Cinctructions
•	10	Nop	Nop	6 instructions
•	11	Nop	Nop	Why insert NOP?
•	12	lvt,-3	lvt,-3	
•	13	Nop	Stp	We let GP start with
•	14	Nop	Nop	these programs and
•	<mark>15</mark> 8 May, 2015	Nop	Nop	el mutate them. 51
•	16	Nop	Nop	

7 Problem Instances

- Problem instances are drawn from a problem class.
- 7 real-valued functions, we will convert to discrete binary optimisations problems for a GA.

number function

1

2

3

4

5

6

7

- Х
- sin2(x/4 16)
- (x 4) * (x 12)
 - (x * x 10 * cos(x))
 - sin(pi*x/64–4) * cos(pi*x/64–12) sin(pi*cos(pi*x/64 – 12)/4) 1/(1 + x /64)

Function Optimization Problem Classes

- 1. To test the method we use binary function classes
- We generate a Normally-distributed value t = -0.7 + 0.5 N (0, 1) in the range [-1, +1].
- 3. We linearly interpolate the value t from the range [1, +1] into an integer in the range [0, 2^{num}-bits
 -1], and convert this into a bit-string t'.
- 4. To calculate the fitness of an arbitrary bit-string x, the **hamming distance** between x and the target bitstring t' is calculated (giving a value in the range [0,numbits]). This value is then **fed into one of the 7 functions.**

Results – 32 bit problems

Problem classes Means and standard deviations	Uniform Mutation	One-point mutation	generated- mutation
p1 mean	30.82	30.96	31.11
p1 std-dev	0.17	0.14	0.16
p2 mean	951	959.7	984.9
p2 std-dev	9.3	10.7	10.8
p3 mean	506.7	512.2	528.9
p3 std-dev	7.5	6.2	6.4
p4 mean	945.8	954.9	978
p4 std-dev	8.1	8.1	7.2
p5 mean	0.262	0.26	0.298
p5 std-dev	0.009	0.013	0.012
p6 mean	0.432	0.434	0.462
p6 std-dev	0.006	0.006	0.004
p7 mean	0.889	0.89	0.901
p ^s 7 ^M std ^D dev John R. W	oodward, Da 0e002	uritz 0.003	0.002

Results – 64 bit problems

Problem classes Means and stand dev	Uniform Mutation	One-point mutation	generated- mutation
p1 mean	55.31	56.08	56.47
p1 std-dev	0.33	0.29	0.33
p2 mean	3064	3141	3168
p2 std-dev	33	35	33
p3 mean	2229	2294	2314
p3 std-dev	31	28	27
p4 mean	3065	3130	3193
p4 std-dev	36	24	28
p5 mean	0.839	0.846	0.861
p5 std-dev	0.012	0.01	0.012
p6 mean	0.643	0.643	0.663
p6 std-dev	0.004	0.004	0.003
p7 mean	0.752	0.7529	0.7684
p7 std-dev	John R. Woodward, Danie 0.0028	el R. Tauritz 0.004	0.0031

p-values T Test for 32 and 64-bit functions on the7 problem classes

	32 bit	32 bit	64 bit	64 bit
class	Uniform	One-point	Uniform	One-point
p1	1.98E-08	0.0005683	1.64E-19	1.02E-05
p2	1.21E-18	1.08E-12	1.63E-17	0.00353
р3	1.57E-17	1.65E-14	3.49E-16	0.00722
p4	4.74E-23	1.22E-16	2.35E-21	9.01E-13
р5	9.62E-17	1.67E-15	4.80E-09	4.23E-06
p6	2.54E-27	4.14E-24	3.31E-24	3.64E-28
р7 8 Мау, 2015	1.34E-24	3.00E-18 John R. Woodward, Daniel F	1.45E-28	5.14E-23

Rebuttal to Reviews

1. Did we test the new mutation operators against standard operators (one-point and uniform mutation) on **different problem classes**?

- NO the mutation operator is designed (evolved) specifically for that class of problem.
- 2. Are we taking the **training stage** into account?
- NO, we are just comparing mutation operators in the testing phase – Anyway how could we meaningfully compare "brain power" (manual design) against "processor power" (evolution).
- 3. Train for all functions NO, we are specializing.

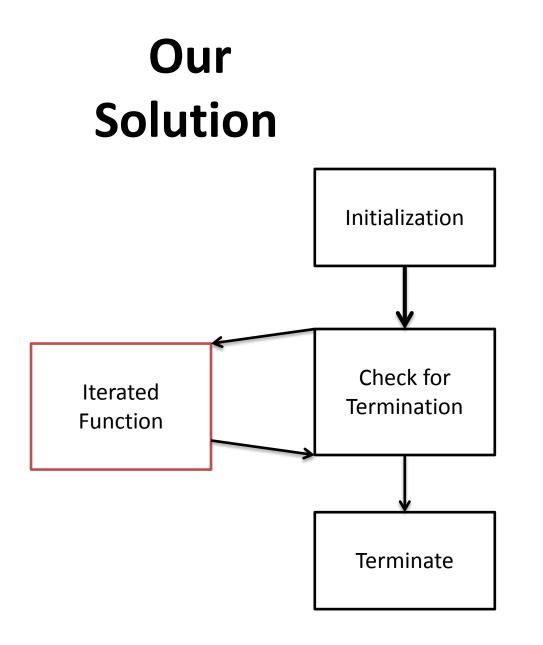
Case Study 4: The Automated Design of Black Box Search Algorithms [21, 23, 25]

Approach

Hyper-Heuristic employing Genetic
 Programing

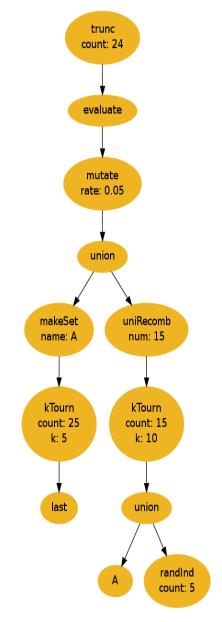
• Post-ordered parse tree

• Evolve the iterated function



Our Solution

- Hyper-Heuristic employing Genetic Programing
- Post-ordered parse tree
- Evolve the iterated function
- High-level primitives



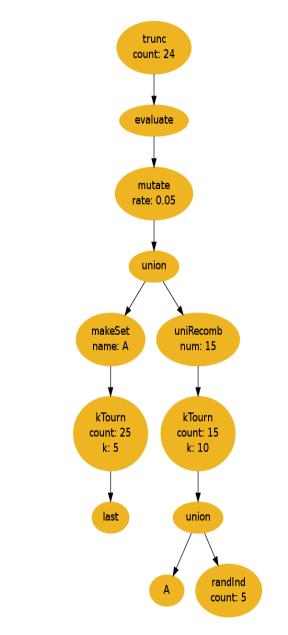
Parse Tree

Iterated function

• Sets of solutions

Function returns

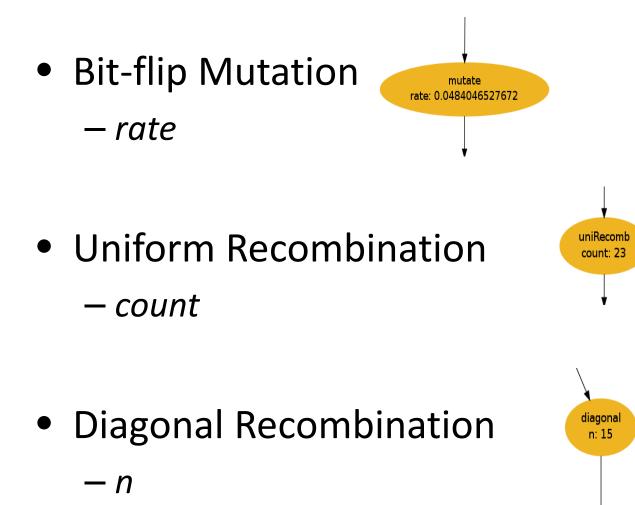
 a set of solutions
 accessible to the
 next iteration



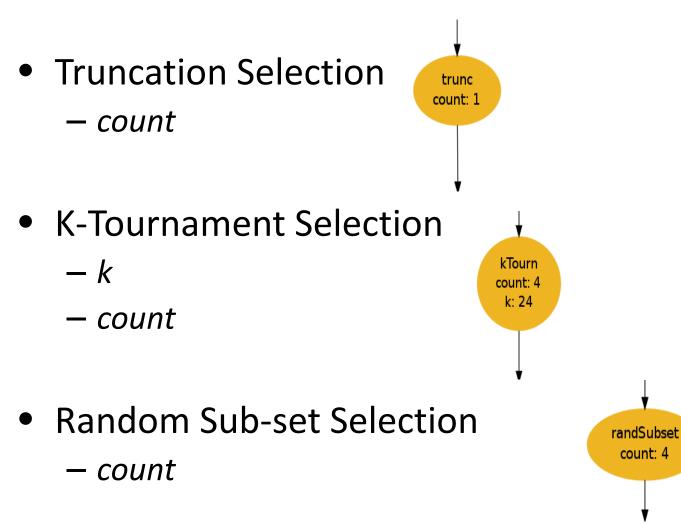
Primitive Types

- Variation Primitives
- Selection Primitives
- Set Primitives
- Evaluation Primitive
- Terminal Primitives

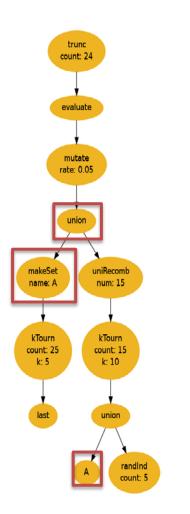
Variation Primitives



Selection Primitives



Set-Operation Primitives



Make Set
 – name

- Persistent
 Sets
 - name
- Union

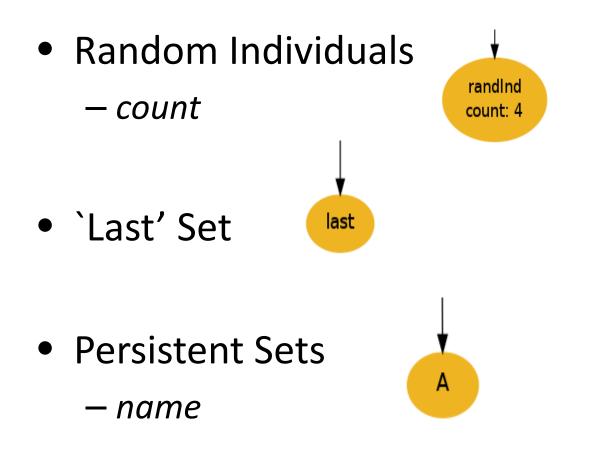
Evaluation Primitive

• Evaluates the nodes passed in

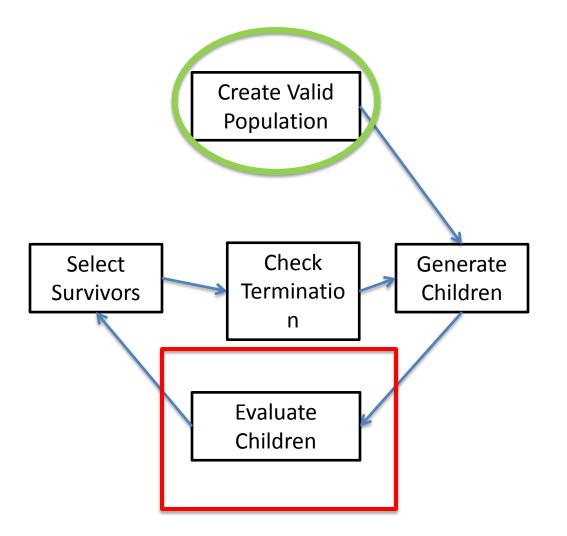
• Allows multiple operations and accurate selections within an iteration

Allows for deception

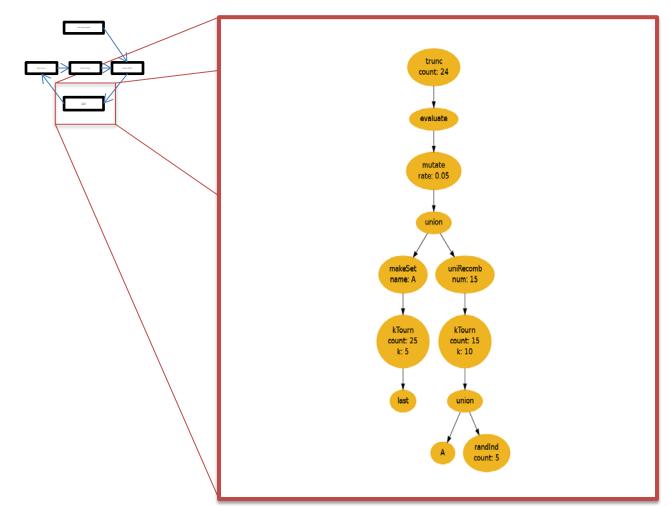
Terminal Primitives



Meta-Genetic Program



BBSA Evaluation



Termination Conditions

• Evaluations

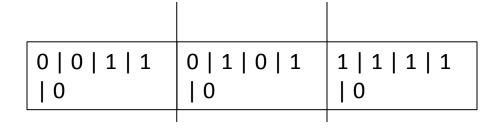
• Iterations

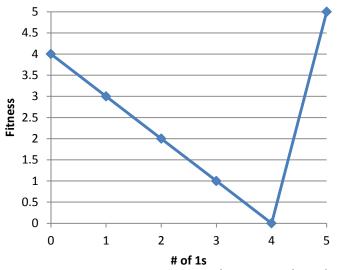
• Operations

• Convergence

Proof of Concept Testing

• Deceptive Trap Problem





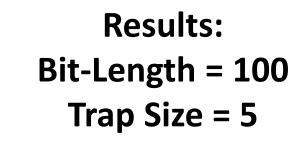
Proof of Concept Testing (cont.)

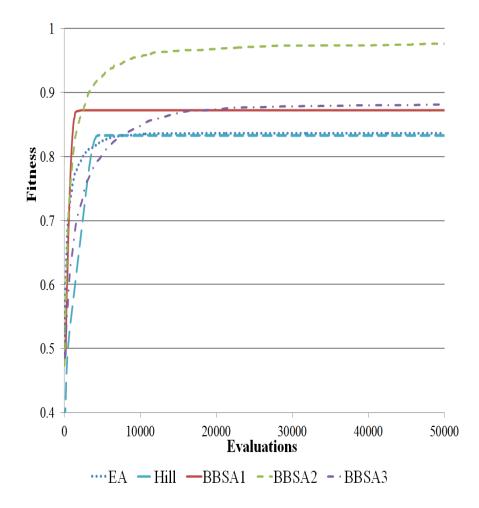
- Evolved Problem Configuration
 - Bit-length = 100
 - Trap Size = 5
- Verification Problem Configurations
 - Bit-length = 100, Trap Size = 5
 - Bit-length = 200, Trap Size = 5
 - Bit-length = 105, Trap Size = 7
 - Bit-length = 210, Trap Size = 7

Results

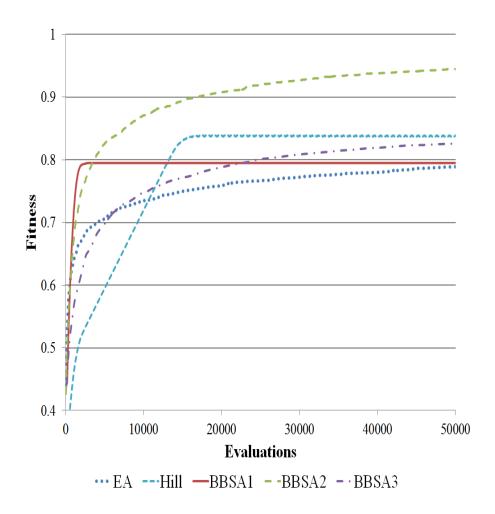
BBSA	EA	Hill-Climber
1	+	+
2	+	+
3	+	+
4	-	-
5	+	+
6	+	+
7	+	+
8	-	-
9	-	-
10	-	-
11	+	+
12	-	-
13	+	+
14	+	+
15	-	-

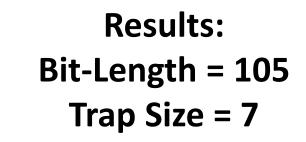
60% Success Rate

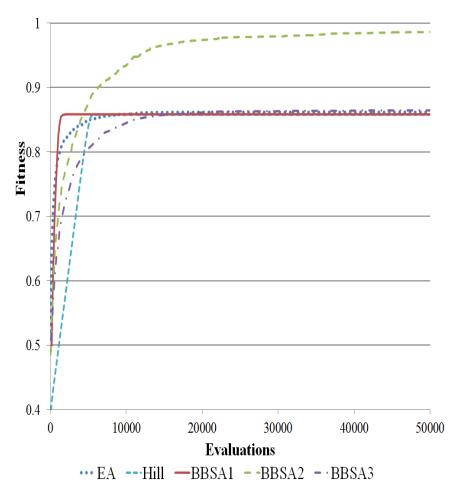


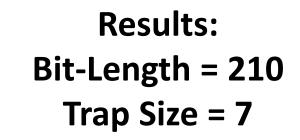


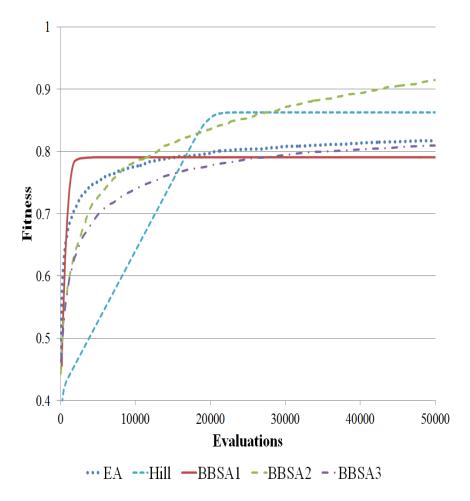
Results: Bit-Length = 200 Trap Size = 5

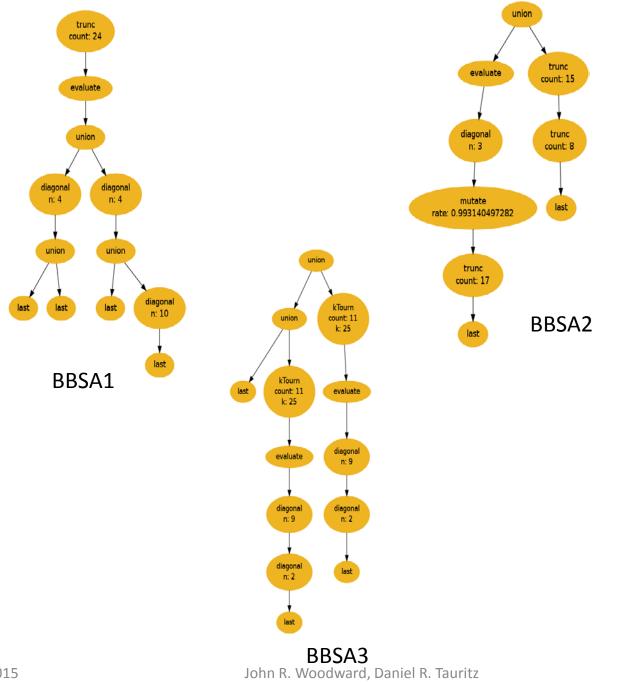






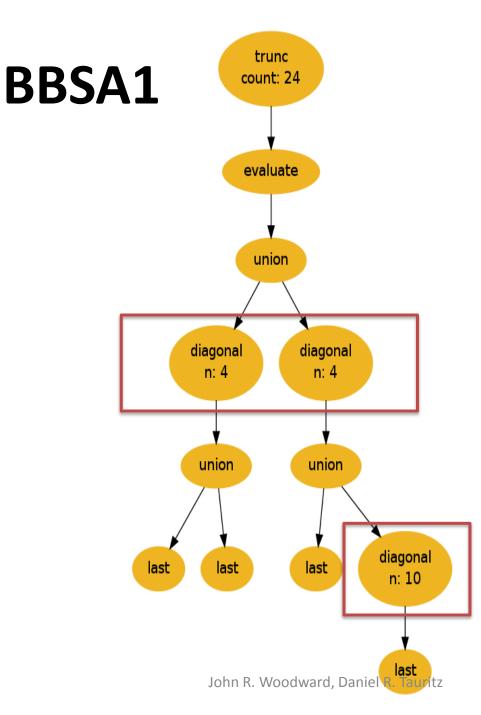


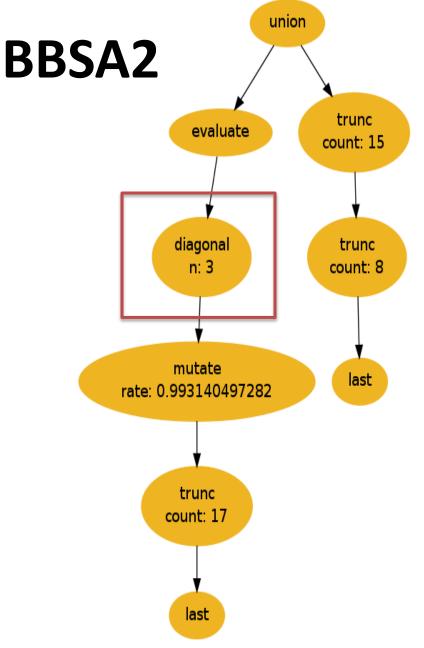


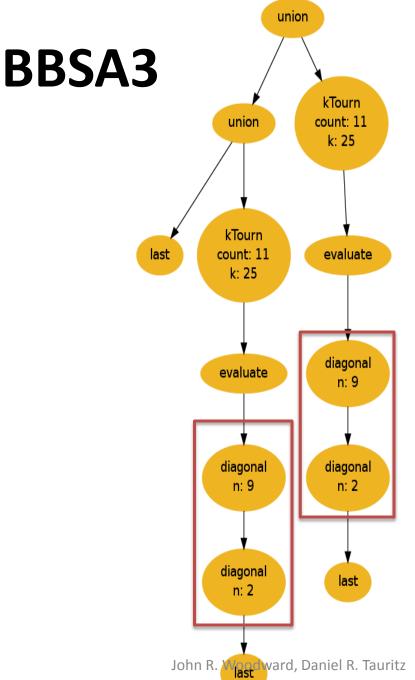


Insights

• Diagonal Recombination



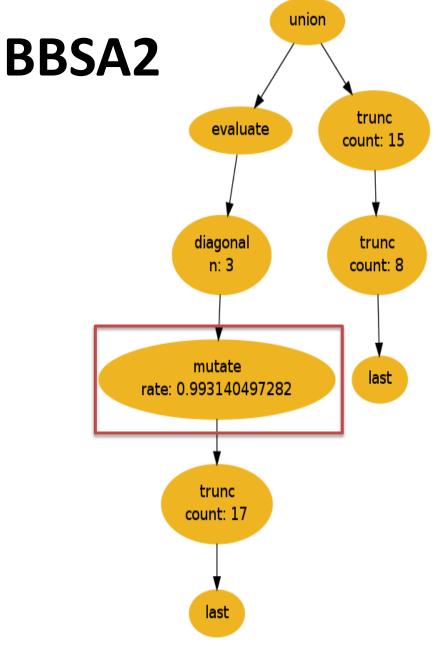




Insights

• Diagonal Recombination

• Generalization



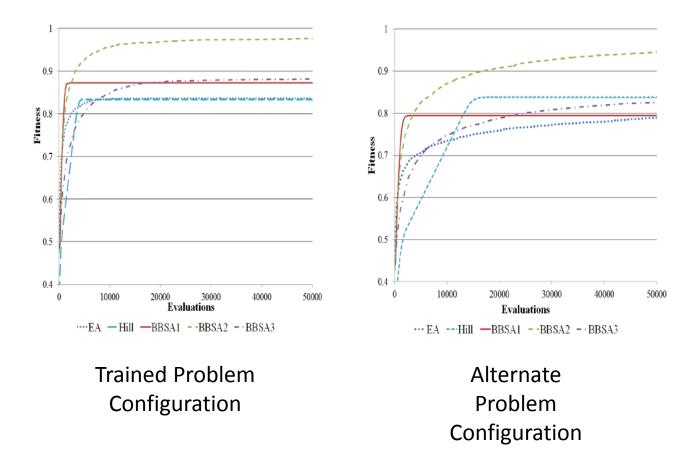
Insights

• Diagonal Recombination

• Generalization

• Over-Specialization

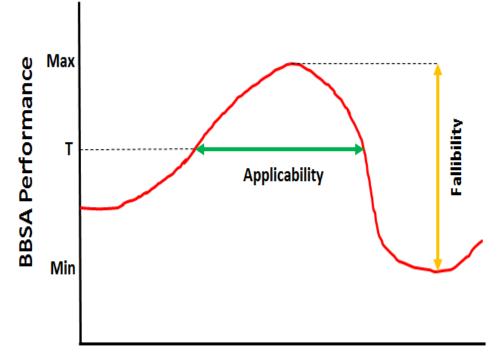
Over-Specialization



Robustness

- Measures of Robustness
 - Applicability
 - Fallibility
- Applicability
 - What area of the problem configuration space do I perform well on?
- Fallibility
 - If a given BBSA doesn't perform well, how much worse will I perform?

Robustness



Problem Configurations

Multi-Sampling

• Train on multiple problem configurations

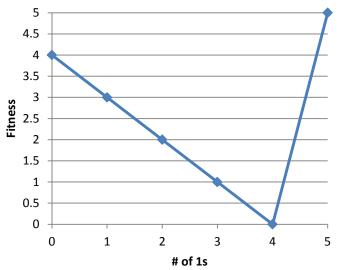
• Results in more robust BBSAs

 Provides the benefit of selecting the region of interest on the problem configuration landscape

Multi-Sample Testing

• Deceptive Trap Problem

0 0 1 1	0 1 0 1 0	1 1 1 1
0	0	0



Multi-Sample Testing (cont.)

- Multi-Sampling Evolution
 Levels 1-5
- Training Problem Configurations
 - 1. Bit-length = 100, Trap Size = 5
 - 2. Bit-length = 200, Trap Size = 5
 - 3. Bit-length = 105, Trap Size = 7
 - 4. Bit-length = 210, Trap Size = 7
 - 5. Bit-length = 300, Trap Size = 5

Initial Test Problem Configurations

- 1. Bit-length = 100, Trap Size = 5
- 2. Bit-length = 200, Trap Size = 5
- 3. Bit-length = 105, Trap Size = 7
- 4. Bit-length = 210, Trap Size = 7
- 5. Bit-length = 300, Trap Size = 5
- 6. Bit-length = 99, Trap Size = 9
- 7. Bit-length = 198, Trap Size = 9
- 8. Bit-length = 150, Trap Size = 5
- 9. Bit-length = 250, Trap Size = 5
- 10. Bit-length = 147, Trap Size = 7
- 11. Bit-length = 252, Trap Size = 7

Initial

Level	Run	Train Fit.	Test Fit.	Fallibility
1	1	1.0	0.976	0.094
1	2	1.0	0.999	8.33 E-3
1	3	0.944	0.883	0.082
1	4	0.976	0.894	0.224
2	1	0.997	0.996	0.023
2	2	0.992	0.959	0.130
2	3	0.966	0.970	0.054
2	4	0.979	0.947	0.120
3	1	0.965	0.966	0.050
3	2	0.984	0.980	0.065
3	3	0.899	0.886	0.059
3	4	0.926	0.898	0.073
4	1	0.976	0.999	5.00 E-3
4	2	0.973	0.969	.0903
4	3	0.982	0.975	0.059
4	4	0.993	0.999	5.00 E-3
5	1	0.973	0.977	0.050
5	2	0.893	0.879	0.035
5	3	0.850	0.850	0.045
5	4	0.955	0.986	0.029

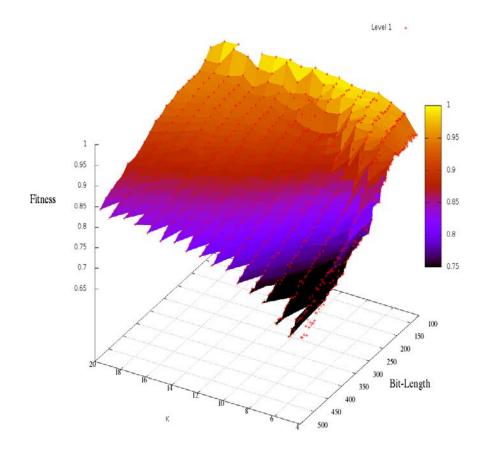
Level	Run	+	\sim	-
1	1	11	0	0
1	2	11	0	0
1	3	11	0	0
1	4	6	2	3
2	1	11	0	0
2	2	11	0	0
2	3	11	0	0
2	4	11	0	0
3	1	11	0	0
3	2	11	0	0
3	3	11	0	0
3	4	11	0	0
4	1	11	0	0
4	2	11	0	0
4	3	11	0	0
4	4	11	0	0
5	1	11	0	0
5	2	10	1	0
5	3	7	4	0
5	4	11	0	0

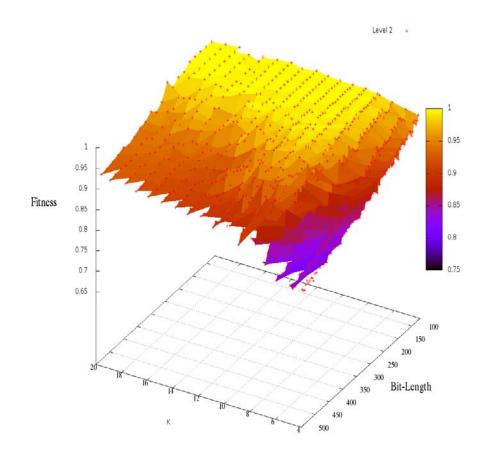
Problem Configuration Landscape Analysis

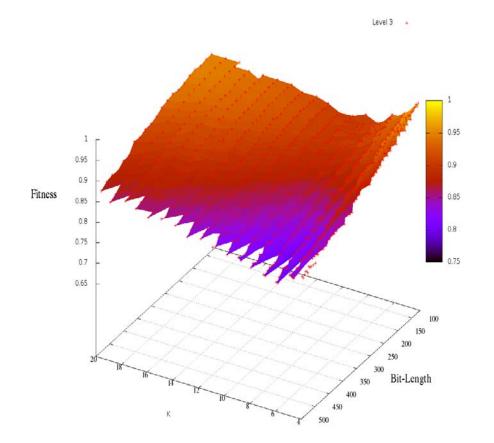
 Run evolved BBSAs on wider set of problem configurations

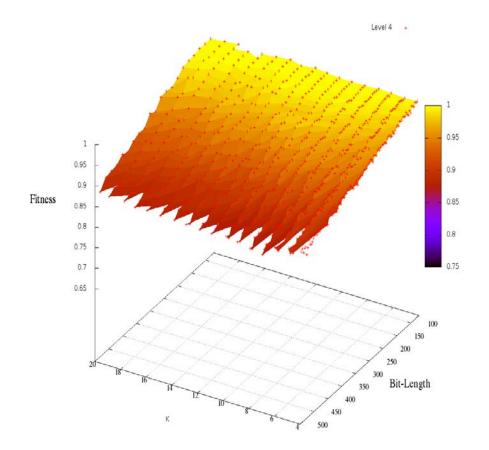
• Bit-length: ~75-~500

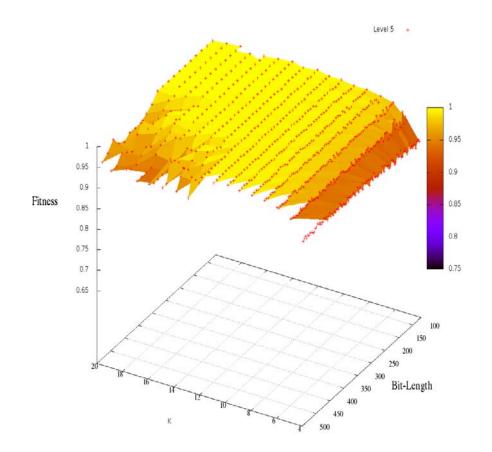
• Trap Size: 4-20



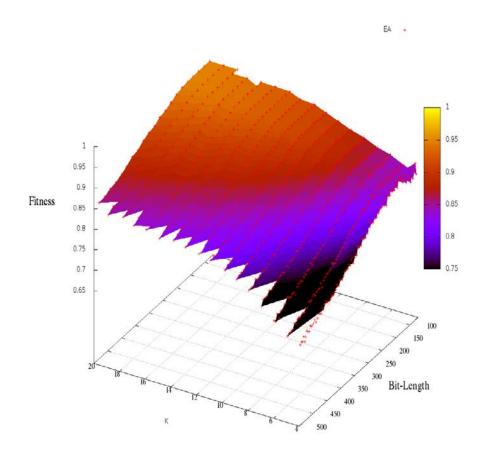








Results: EA Comparison



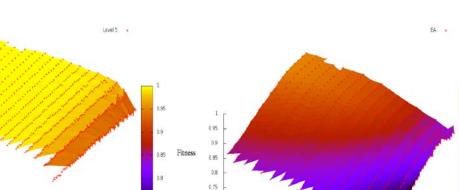
Discussion

Robustness

- Fallibility

Robustness: Fallibility

Multi-Sample Level 5



0.7

0.65

150

200

Bit-Length

350

Standard EA

0.95

0.9

0.85

0.8

150

200

Bit-Length

0.95

0.9

0.85

0.8

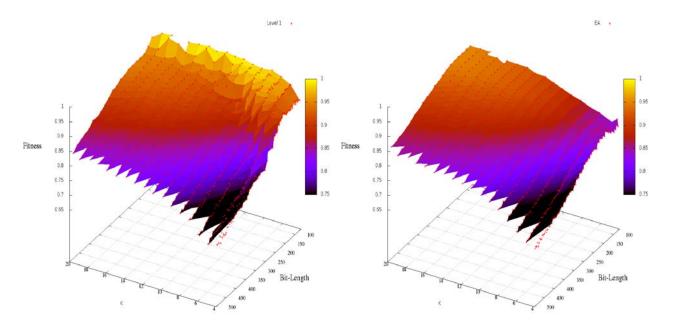
0.75

0.7

Fitness

Robustness: Fallibility

Multi-Sample Level 1



Standard EA

Discussion

• Robustness

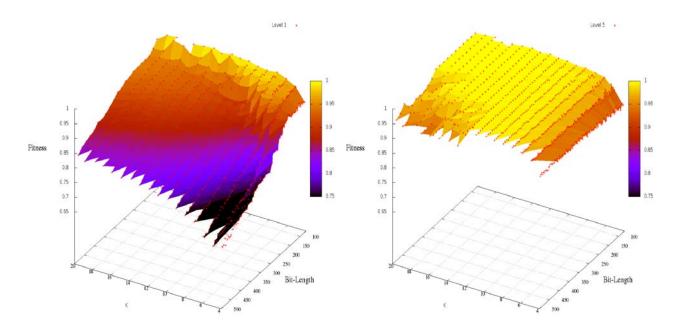
• Fallibility

• Applicability

Robustness: Applicability

Multi-Sample Level 1

Multi-Sample Level 5



Robustness: Applicability

Level	Run	Train Fit.	Test Fit.	Fallibility
5	1	0.973	0.977	0.050
5	2	0.893	0.879	0.035
5	3	0.850	0.850	0.045
5	4	0.955	0.986	0.029

Drawbacks

- Increased computational time
 - More runs per evaluation (increased wall time)
 - More problem configurations to optimize for (increased evaluations)

Summary of Multi-Sample Improvements

Improved Hyper-Heuristic to evolve more robust BBSAs

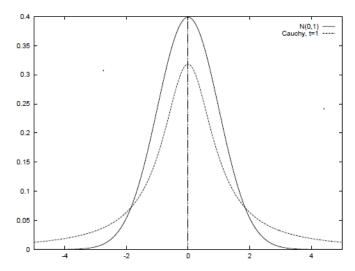
 Evolved custom BBSA which outperformed standard EA and were robust to changes in problem configuration

Case Study 5: The Automated Design of Mutation Operators for Evolutionary Programming

Designing Mutation Operators for Evolutionary Programming [18]

- **1.** Evolutionary programing optimizes functions by evolving a population of real-valued vectors (genotype).
- Variation has been provided (manually) by probability distributions (Gaussian, Cauchy, Levy).
- 3. We are **automatically generating** probability distributions (using genetic programming).
- Not from scratch, but from already well known distributions (Gaussian, Cauchy, Levy). We are "genetically improving probability distributions".
- 5. We are evolving mutation operators **for a problem class** (a probability distributions over functions).
- 6. ଃNØ₂€ROSSOVER

Genotype is (1.3,...,4.5,...,8.7) Before mutation



Genotype is (1.2,...,4.4,...,8.6) After mutation

(Fast) Evolutionary Programming

Heart of algorithm is mutation SO LETS AUTOMATICALLY DESIGN

 $x_i'(j) = x_i(j) + \eta_i(j)D_j$

- 1. EP mutates with a Gaussian
- 2. FEP mutates with a Cauchy
- A generalization is mutate with a distribution D (generated with genetic programming)

- 1. Generate the initial population of μ individuals, and set k = 1. Each individual is taken as a pair of real-valued vectors, $(x_i, \eta_i), \forall i \in \{1, \dots, \mu\}$.
- Evaluate the fitness score for each individual (x_i, η_i), ∀i ∈ {1, · · · , μ}, of the population based on the objective function, f(x_i).
- 3. Each parent (x_i, η_i) , $i = 1, \dots, \mu$, creates a single offspring (x_i', η_i') by: for $j = 1, \dots, n$,

$$\begin{aligned} x_i'(j) &= x_i(j) + \eta_i(j)N(0,1), \quad (1) \\ \eta_i'(j) &= \eta_i(j)\exp(\tau'N(0,1) + \tau N_j(0,1)) \quad (2) \end{aligned}$$

where $x_i(j)$, $x_i'(j)$, $\eta_i(j)$ and $\eta_i'(j)$ denote the *j*-th component of the vectors x_i , x_i' , η_i and η_i' , respectively. N(0,1) denotes a normally distributed onedimensional random number with mean zero and standard deviation one. $N_j(0,1)$ indicates that the random number is generated anew for each value of *j*. The factors τ and τ' have commonly set to $\left(\sqrt{2\sqrt{n}}\right)^{-1}$ and $\left(\sqrt{2n}\right)^{-1}$ [9, 8].

- 4. Calculate the fitness of each offspring $(x_i', \eta_i'), \forall i \in \{1, \cdots, \mu\}$.
- 5. Conduct pairwise comparison over the union of parents (x_i, η_i) and offspring (x_i', η_i') , $\forall i \in \{1, \dots, \mu\}$. For each individual, q opponents are chosen randomly from all the parents and offspring with an equal probability. For each comparison, if the individual's fitness is no greater than the opponent's, it receives a "win."
- Select the μ individuals out of (x_i, η_i) and (x_i', η_i'), ∀i ∈ {1, · · · , μ}, that have the most wins to be parents of the next generation.

7. Stop if the stopping criterion is satisfied; otherwise,

Optimization & Benchmark Functions

A set of 23 benchmark functions is typically used in the literature. **Minimization** $\forall x \in S : f(x_{min}) \leq f(x)$ We use them as **problem classes**.

Table 1: The 23 test functions used in our experimental studies, where n is the dimension of the function, f_{min} the minimum value of the function, and $S \subseteq \mathbb{R}^n$.

the minimum funce of the function, and b = it i			
Test function	n	S	f_{min}
$f_1(x) = \sum_{i=1}^n x_i^2$	30	$[-100, 100]^n$	0
$f_{2}(x) = \sum_{i=1}^{n} x_{i} + \prod_{i=1}^{n} x_{i} $	30	$[-10, 10]^n$	0
$f_3(x) = \sum_{i=1}^n (\sum_{j=1}^i x_j)^2$	30	$[-100, 100]^n$	0
$f_4(x) = \max_i\{ x_i , 1 \le i \le n\}$	30	$[-100, 100]^n$	0
$f_5(x) = \sum_{i=1}^{n-1} [100(x_{i+1} - x_i^2)^2 + (x_i - 1)^2]$	30	$[-30, 30]^n$	0
$f_6(x) = \sum_{i=1}^n \lfloor x_i + 0.5 \rfloor$	30	$[-100, 100]^n$	0
$f_7(x) = \sum_{i=1}^{n} ix_i^4 + random[0, 1)$	30	$[-1.28, 1.28]^n$	0
$f_8(x) = \sum_{i=1}^{n} -x_i \sin(\sqrt{ x_i })$	30	$[-500, 500]^n$	-12569.5
$f_9(x) = \sum_{i=1}^{n} [x_i^2 - 10\cos(2\pi x_i) + 10)]$	30	$[-5.12, 5.12]^n$	0
$f_{10}(x) = -20 \exp\left(-0.2\sqrt{\frac{1}{n}\sum_{i=1}^{n} x_i^2}\right) - \exp\left(\frac{1}{n}\sum_{i=1}^{n} \cos 2\pi x_i\right)$	30	$[-32, 32]^n$	0
+20 + e			

Function Class 1

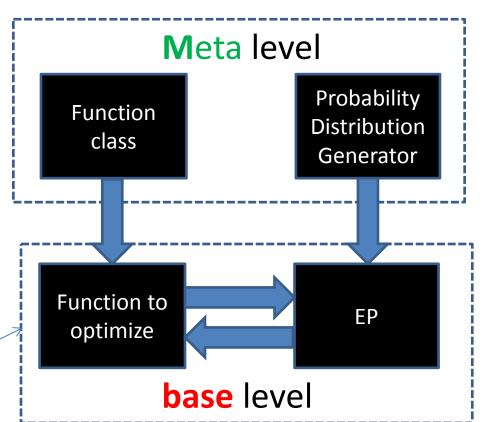
- 1. Machine learning needs to generalize.
- 2. We generalize to function classes.
- 3. $y = x^2$ (a function)
- 4. $y = ax^2$ (parameterised function)
- 5. $y = ax^2$, *a* ~[1,2] (function class)
- 6. We do this for all benchmark functions.
- 7. The mutation operators is evolved to fit the probability distribution of functions.

Function Classes 2

Function Classes	S	b	f_{min}
$f_1(x) = a \sum_{i=1}^n x_i^2$	$[-100, 100]^n$	N/A	0
$f_2(x) = a \sum_{i=1}^{n} x_i + b \prod_{i=1}^{n} x_i $	$[-10, 10]^n$	$b \in [0, 10^{-5}]$	0
$f_3(x) = \sum_{i=1}^n (a \sum_{j=1}^i x_j)^2$	$[-100, 100]^n$	N/A	0
$f_4(x) = \max_i \{ a \mid x_i \mid , 1 \le i \le n \}$	$[-100, 100]^n$	N/A	0
$f_5(x) = \sum_{i=1}^{n} \left[a(x_{i+1} - x_i^2)^2 + (x_i - 1)^2 \right]$	$[-30, 30]^n$	N/A	0
$f_6(x) = \sum_{i=1}^n (\lfloor ax_i + 0.5 \rfloor)^2$	$[-100, 100]^n$	N/A	0
$f_7(x) = a \sum_{i=1}^{n} ix_i^4 + random[0, 1)$	$[-1.28, 1.28]^n$	N/A	0
$f_8(x) = \sum_{i=1}^n -(x_i \sin(\sqrt{ x_i }) + a)$	$[-500, 500]^n$	N/A	[-12629.5,
			-12599.5]
$f_9(x) = \sum_{i=1}^{n} \left[ax_i^2 + b(1 - \cos(2\pi x_i)) \right]$	$[-5.12, 5.12]^n$	$b \in [5, 10]$	0
$f_{10}(x) = -a \exp(-0.2\sqrt{\frac{1}{n}\sum_{i=1}^{n} x_i^2})$	$[-32, 32]^n$	N/A	0
$-\exp(\frac{1}{n}\sum_{i=1}^{n}\cos 2\pi x_i) + a + e$			

Meta and Base Learning

- At the **base** level we are learning about a **specific** function.
- At the meta level we are learning about the problem class.
- We are just doing "generate and test" at a higher level
- What is being passed with each **blue arrow**?
- Conventional EP



Compare Signatures (Input-Output)

Evolutionary Programming

 $(R^n \rightarrow R) \rightarrow R^n$

- **Input** is a function mapping real-valued vectors of length n to a real-value.
- **Output** is a (near optimal) real-valued vector
- (i.e. the <u>solution</u> to the problem <u>instance</u>)

Evolutionary Programming

 $\frac{\text{Designer}}{[(R^n \rightarrow R)]} \rightarrow ((R^n \rightarrow R) \rightarrow R^n)$

Input is a *list of* functions mapping real-valued vectors of length n to a real-value (i.e. sample problem instances from the problem class).

Output is a (near optimal) (mutation operator for) Evolutionary Programming

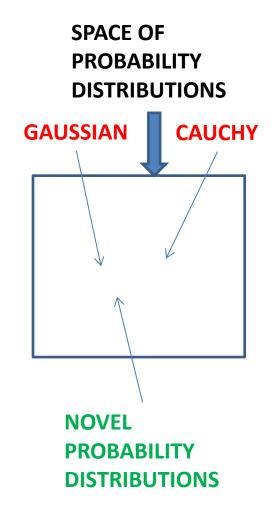
(i.e. the <u>solution</u> <u>method</u> to the problem <u>class</u>)

We are **raising the level of generality** at which we operate.

Genetic Programming to Generate Probability Distributions

- 1. GP Function Set {+, -, *, %}
- 2. GP **Terminal Set** {N(0, random)} N(0,1) is a normal distribution.
- For example a Cauchy distribution is generated by N(0,1)%N(0,1).

Hence **the search space of probability distributions** contains the two existing probability distributions used in EP but also **novel probability distributions**.



Means and Standard Deviations

These results are good for two reasons.

- **1. starting** with a manually designed distributions (Gaussian).
- 2. evolving distributions for each function class.

Function	FI	ΞP	C	EP	GP-distribution			
Class	$Mean \ Best$	$Std \ Dev$	Mean Best	$Std \ Dev$	$Mean \ Best$	Std Dev		
10 A					6.37×10^{-5}			
					8.14×10^{-4}			
					6.14×10^{-3}			
					2.16×10^{-1}			
10 C.					8.39×10^{-7}			
f_6	3.86×10^{-2}	3.12×10^{-2}	4.40×10	1.42×10^{2}	9.20×10^{-3}	1.34×10^{-2}		
f_7	6.49×10^{-2}	1.04×10^{-2}	6.64×10^{-2}	1.21×10^{-2}	5.25×10^{-2}	8.46×10^{-3}		
					-12611.6			
10 C	6.24×10^{-2}				1.74×10^{-3}			
f_{10}	1.67	4.26×10^{-1}	1.45	2.77×10^{-1}	1.38	2.45×10^{-1}		

T-tests

Table 5 2-tailed t-tests comparing EP with GP-distributions, FEP and CEP on f_1 - f_{10} .

Function Class	Number of Generations		$\begin{array}{l} \text{GP-distribution vs CEP} \\ \textit{t-test} \end{array}$
f_1	1500	2.78×10^{-47}	4.07×10^{-2}
f_2	2000	5.53×10^{-62}	1.59×10^{-54}
f_3	5000	8.03×10^{-8}	1.14×10^{-3}
f_4	5000	1.28×10^{-7}	3.73×10^{-36}
f_5	20000	2.80×10^{-58}	9.29×10^{-63}
f_6	1500	1.85×10^{-8}	3.11×10^{-2}
f_7	3000	3.27×10^{-9}	2.00×10^{-9}
f_8	9000	7.99×10^{-48}	5.82×10^{-75}
f_9	5000	6.37×10^{-55}	6.54×10^{-39}
f_{10}	1500	9.23×10^{-5}	1.93×10^{-1}

Performance on Other Problem Classes

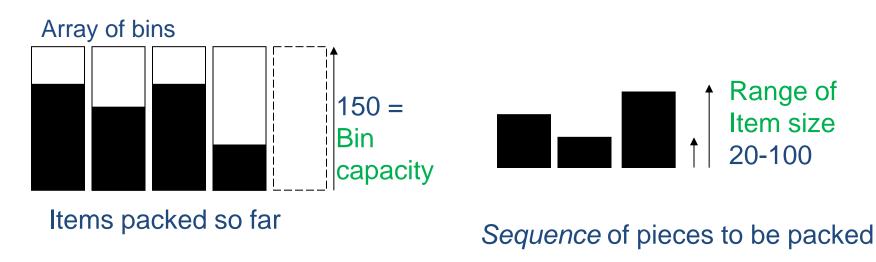
Table 8: This table compares the fitness values (averaged over 20 runs) of each of the 23 ADRs on each of the 23 function classes. Stardard deviations are in parentheses.

	ADRI A	ADR2	ADR3	ADR4	ADR5	ADR6	ADR7	ADR8	ADR9	ADR10	ADR11	ADR12	ADR13	ADR14	ADR15	ADR16	ADR17	ADR18	ADR19	ADR20	ADR21	ADR22	ADR23
Л	3.796042378 3 (15.53395359)()																						
J ₂	0.03272533 0																						
ſ3	0.059115953 0																						
<i>f</i> 4	17.25966091 1																						
J5	-12.59873403 -1																						7 -7.353638881 7)(20.10064511)
<i>I</i> 6	422.0335 1 (1649.46925) (2		12.165	0.135 9)(0.26472428	0.058	0.0535 8)(0.22285881)	0.11 8)(0.30461364)	9.298 7)(6.862988915	0.107 i)(0.25034923)	0.015	0.3255	0.039 3)(0.061034934	0.035 0(0.06645140	0.0315 7)(0.02455391)	195.777 5)(490.122037	17987.881 1)(13480.8209)	37431.6995 2)(19447.5181		375.2155 3)(888.000648	0.017	4999.8915 7)(5268.862537	185.43 7)(446.236636	83.996 2)(123.8021751)
ħ	0.065542671 0																						0.186500061 8)(0.111182366)
J ₈	-7476.802093 -7																						
ſŋ	-6.364340621 -6 (13.55211805)(1																						
<i>J</i> 10	-26.54875358 -2																						
<i>f</i> 11	-0.651086092 -0																						
<i>J</i> ₁₂	2.375745683 1. (2.850960856)(2																						
<i>J</i> 13	7.528102918 1 (11.50730323)(1																						
<i>J</i> 14	1.734470721 1.																						
<i>J</i> ₁₅	0.000643324 0																						
<i>f</i> ₁₆	-1.92447213 -1	1.924473263	-1.92447087	5 -1.92446820	7 -1.924439114	4 -1.92442900	1 -1.92445566	4 -1.924280681	-1.92447351	5 -1.924473529	-1.92445427	5 -1.924473348	-1.92447290	4 -1.92447222	4 -1.92447211	3 -1.92447354	3 -1.92447336	-1.92447250	5 -1.92447354	3 -1.92447352	8 -1.924473215	5 -1.92447301	6 -1.92447352
<i>f</i> ₁₇	3.786952682 3																						
<i>f</i> 18	4.575031533 4 (1.117668123)(1	57 497 1819	4.575098811	4.575282035	4.5763558	4.577539016	4.575858015	4.588715133	4.574958404	4.574958205	4.576371722	4.574967813	4.575001205	4.575011001	4.575028689	6.005761337	4.574969199	4.575008958	4.57495705	4.574957813	4.574974777	4.574979692	4.57495876
<i>/</i> 19	-3.552067105 -3 (1.905081577)	3.552080968	-3.55205040	8 -3.55199694		3 -3.53867043	4 -3.55188299							-									3 -3.552083673 5)(1.903090478)

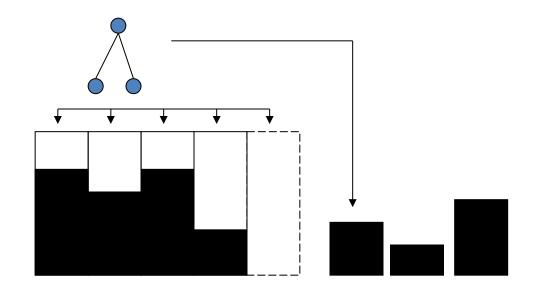
Case Study 6: The Automated Design of On-Line Bin Packing Algorithms

On-line Bin Packing Problem [9,11]

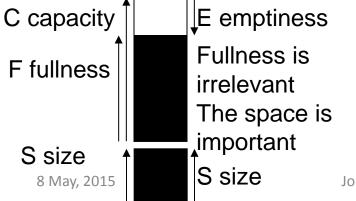
- A *sequence* of items packed into as few a bins as possible.
- Bin size is 150 units, items uniformly distributed between 20-100.
- Different to the off-line bin packing problem where the set of items.
- The "best fit" heuristic, places the current item in the space it fits best (leaving least slack).
- It has the property that this heuristic does not open a new bin unless it is forced to.



Genetic Programming applied to on-line bin packing

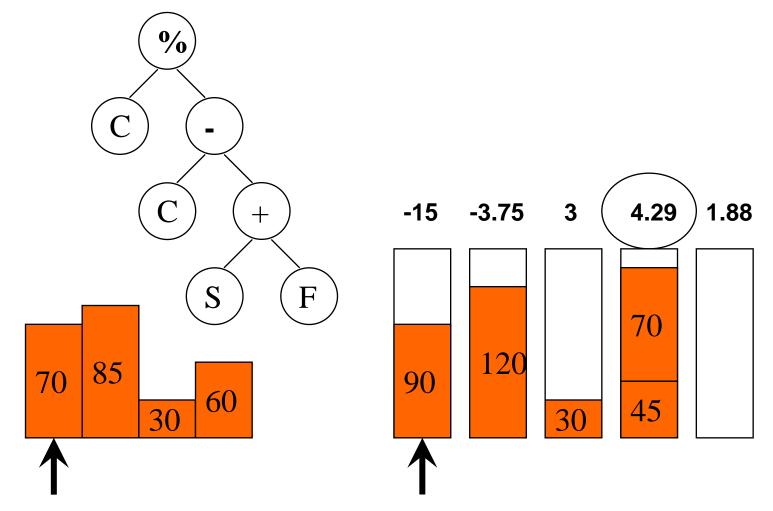


Not obvious how to link Genetic Programming to combinatorial problems. The GP tree is applied to each bin with the current item and placed in the bin with The maximum score



Terminals supplied to Genetic Programming Initial representation {C, F, S} Replaced with {E, S}, E=C-F

How the heuristics are applied (skip)

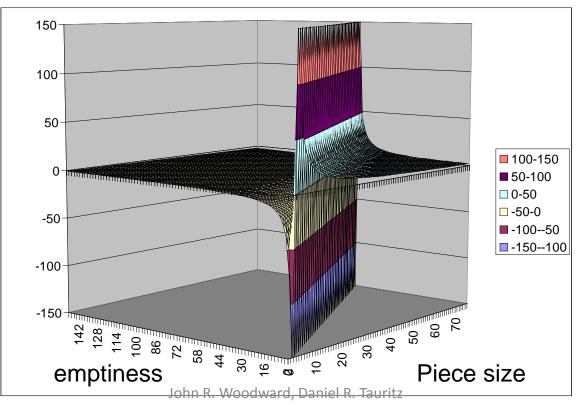


The Best Fit Heuristic

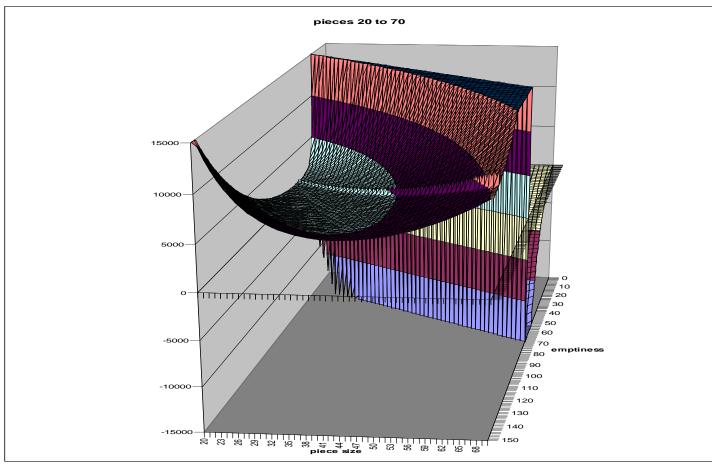
Best fit = 1/(E-S). Point out features.

Pieces of size S, which fit well into the space remaining E, score well.

Best fit applied produces a set of points on the surface, The bin corresponding to the maximum score is picked.



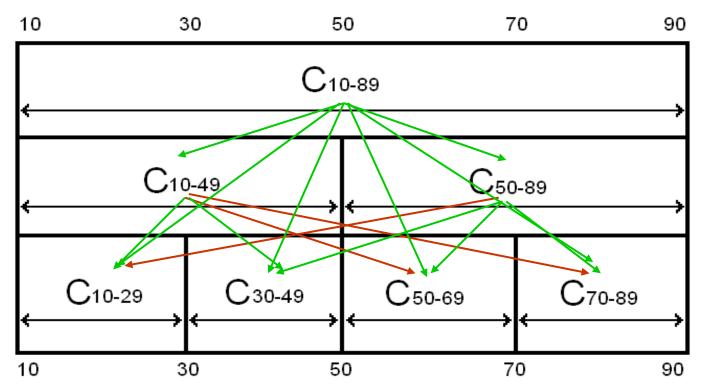
Our best heuristic.



Similar shape to best fit – but curls up in one corner. Note that this is rotated, relative to previous slide.

Robustness of Heuristics

= all legal results = some illegal results



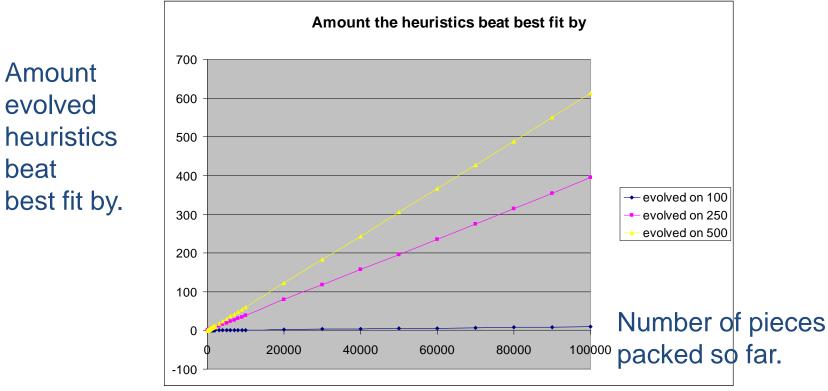
Testing Heuristics on problems of much larger size than in training

Table I	H trained100	H trained 250	H trained 500
100	0.427768358	0.298749035	0.140986023
1000	0.406790534	0.010006408	0.000350265
10000	0.454063071	2.58E-07	9.65E-12
100000	0.271828318	1.38E-25	2.78E-32

Table shows p-values using the best fit heuristic, for heuristics trained on different size problems, when applied to different sized problems

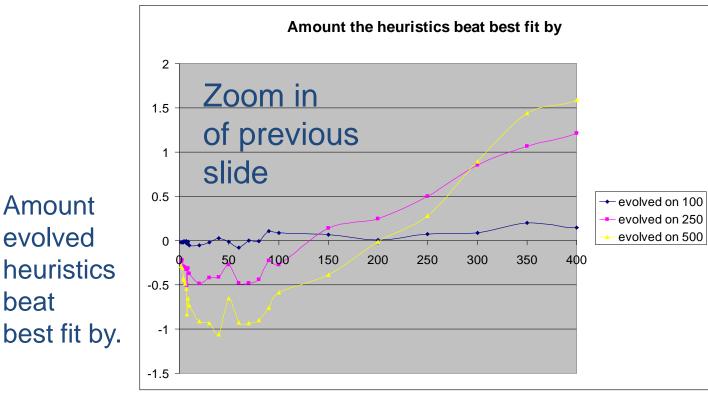
- 1. As number of items trained on increases, the probability decreases (see next slide).
- 2. As the number of items packed increases, the probability decreases (see next slide).

Compared with Best Fit



- Averaged over 30 heuristics over 20 problem instances
- Performance does not deteriorate
- The larger the training problem size, the better the bins are packed.

Compared with Best Fit



- The heuristic seems to learn the number of pieces in the problem
- Analogy with sprinters running a race accelerate towards end of race.
- The "break even point" is approximately half of the size of the training problem size
- If there is a gap of size 30 and a piece of size 20, it would be better to wait for a better piece to come along later about 10 items (similar effect at upper bound?).

Hyper-heuristics Visualization Demo

Step by Step Guide to Automatic Design of Algorithms [8, 12]

- 1. Study the literature for existing heuristics for your chosen domain (manually designed heuristics).
- 2. Build an algorithmic framework or template which expresses the known heuristics.
- 3. Let metaheuristics (e.g. Genetic Programming) search for variations on the theme.
- 4. Train and test on problem instances drawn from the same probability distribution (like machine learning). Constructing an optimizer is machine learning (this approach prevents "cheating").

A Brief History (Example Applications) [5]

- 1. Image Recognition Roberts Mark
- 2. Travelling Salesman Problem Keller Robert
- **3.** Boolean Satisfiability Holger Hoos, Fukunaga, Bader-El-Den
- 4. Data Mining Gisele L. Pappa, Alex A. Freitas
- 5. Decision Tree Gisele L. Pappa et al
- 6. Crossover Operators Oltean et al, Daniel Tauritz et al
- 7. Selection Heuristics Woodward & Swan, Daniel Tauritz et al
- 8. Bin Packing 1,2,3 dimension (on and off line) Edmund Burke et. al. & Riccardo Poli et al
- 9. Bug Location Shin Yoo
- 10. Job Shop Scheduling Mengjie Zhang
- 11. Black Box Search Algorithms Daniel Tauritz et al

Comparison of Search Spaces

- If we tackle a problem instance directly, e.g. Travelling Salesman Problem, we get a combinatorial explosion. The search space consists of *solutions*, and therefore explodes as we tackle larger problems.
- If we tackle a generalization of the problem, we do not get an explosion as the distribution of functions expressed in the search space tends to a limiting distribution. The search space consists of *algorithms to produces solutions* to a problem instance of any size.
- The algorithm to tackle TSP of size 100-cities, is the same size as The algorithm to tackle TSP of size 10,000-cities

A Paradigm Shift?

One person proposes one algorithm and tests it in isolation. One person proposes a family of algorithms and tests them in the context of a problem class.

Human cost (INFLATION) conventional approach machine cost MOORE'S LAW new approach

- Previously one person proposes one algorithm
- Now one person proposes a set of algorithms
- Analogous to "industrial revolution" from hand made to machine made. Automatic Design.

Conclusions

- Heuristic are trained to fit a problem class, so are designed in context (like evolution). Let's close the feedback loop! Problem instances live in classes.
- 2. We can design algorithms on **small** problem instances and **scale** them apply them to **large** problem instances (TSP, child multiplication).

Overview of Applications

	SELECTION	MUTATION GA	BIN PACKING	MUTATION EP	CROSSOVER	BBSA
Scalable performance	Not yet tested	Not yet tested	Yes - why	No - why	Not yet tested	Yes
Generation zero human comp.	Rank, fitness proportional	No – needed to seed	Best fit	Gaussian and Cauchy	No	No
Problem classes tested	Shifted function	Parameterized function	Item size	Parameterized function	Rosenbrock, NK-Landscapes, Rastrigin, etc.	DTrap, NK- landscapes
Results Human Competitive	Yes	Yes	Yes	Yes	Yes	Yes
Algorithm iterate over	Population	Bit-string	Bins	Vector	Pair of parents	Population
Search Method	Random Search	Iterative Hill- Climber	Genetic Programming	Genetic Programming	Linear Genetic Programming	Tree-based GP
Type Signatures	R^2->R	B^n->B^n	R^3->R	()->R	R^n -> R^m	Population -> Population
Reference	[16]	[15]	[6,9,10,11]	[18]	[20]	[21,23,25]

SUMMARY

- 1. We can automatically design algorithms that **consistently outperform human designed algorithms (on various domains)**.
- 2. Humans should not provide variations- genetic programing can do that.
- 3. We are altering the heuristic to suit the set of problem instances presented to it, in the hope that it will generalize to new problem instances (same distribution central assumption in machine learning).
- 4. The "best" heuristics depends on the set of problem instances. (feedback)
- 5. Resulting algorithm is part man-made part machine-made (synergy)
- 6. not evolving from scratch like Genetic Programming,
- 7. improve existing algorithms and adapt them to the new problem instances.
- 8. Humans are working at a higher level of abstraction and more creative. Creating search spaces for GP to sample.
- 9. Algorithms are **reusable**, "solutions" aren't. (e.g. tsp algorithm vs route)
- 10. Opens up new problem domains. E.g. bin-packing.

Related hyper-heuristics events

- Evolutionary Computation for the Automated Design of Algorithms (ECADA) workshop @GECCO 2015
- Combinatorial Black Box Optimization Competition (CBBOC) @GECCO 2015

End of File 😳

- Thank you for listening !!!
- We are glad to take any
 - comments (+,-)
 - suggestions/criticisms
 - Please email us any missing references!

John Woodward (<u>http://www.cs.stir.ac.uk/~jrw/</u>)

Daniel Tauritz (<u>http://web.mst.edu/~tauritzd/</u>)

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