## Calculating Games with Higher-Order Functions

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(based on joint work with M. Escardó)

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## Outline

(1) Game Theory
(2) Quantifiers and Selection Functions
(3) Generalisation
(4) Monads

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(1) Game Theory
(2) Quantifiers and Selection Functions

3 Generalisation
(4) Monads

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## Game Theory

- Early development in the 19th century
- Formal approach with von Neumann (1930's)


John von Neumann

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- $n$ players
- $n$ strategy sets $X_{1}, \ldots, X_{n}$
- payoff function $q: \vec{X} \rightarrow \mathbb{R}^{n}$


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How should players choose their strategies in order to maximise their individual payoffs?

## Game Theory



过

## Game Theory



Two players
Strategy sets $X_{1}=X_{2}=\{L, R\}$
Payoff function

| $f$ | $L$ | $R$ |
| :---: | :---: | :---: |
| $L$ | $(1,0)$ | $(0,1)$ |
| $R$ | $(0,1)$ | $(1,0)$ |

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The "penalty" example shows that strategy profiles in equilibrium not necessarily exist either

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i.e. player chooses probability distribution on strategies


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## Theorem (Nash)

Mixed strategies in equilibrium always exist

The "penalty" example is again an illustration of this:
Players randomly choosing left or right is best they can do

## Simultaneous versus Sequential Games

- That's all in the case of simultaneous games
- With sequential games things are simpler and nicer
- Strategies: mappings from previous moves to current move
- Similar definition of Nash equilibrium


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But equilibrium always exists and can be computed by a technique called backward induction

## Backward Induction

$$
q: X \times Y \times Z \rightarrow \mathbb{R}^{3}
$$



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$\xrightarrow[+]{+}$

## Our Recent Work

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1. Generalised notions of sequential game, Nash equilibrium and backward induction
2. Showed how general notions appear in topology, proof theory, and algorithms, amongst others


## Outline

(1) Game Theory
(2) Quantifiers and Selection Functions
(3) Generalisation
(4) Monads
$\stackrel{+}{\square}$

## Single-player Games

SUDOKU 数独 Time: $\begin{array}{r}\text { HARD } \\ \text { H: }\end{array}$

| 8 |  | 4 |  | 2 | 9 | 4 |  | 6 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 2 | 5 | 7 | 4 | 1 | 4 |  | 9 | 7 |
| 9 |  |  | 1 | 5 | 8 |  | 3 | 4 |
| 5 | 2 | 6 | 7 | 7 |  | 2 | 1 | 3 |
| 4 |  | 6 |  | 9 |  | 7 |  | 8 |
| 1 | 1 | 3 | 2 | $4^{3}$ | $4^{3}$ | 7 |  | 5 |
|  | 9 | 2 | 3 |  | 4 | 5 | ${ }^{3}$ | 6 |
| ${ }^{3}$ | 6 | 5 |  |  | 1 | 3 | 2 | 1 |
| ${ }^{3}$ | 1 | 4 | 7 |  | 9 | 4 | 7 | 2 |



## Two-player Games

Two players: Black and White


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Possible outcomes:

- Black wins
- White wins
- Draw



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Strategy: Choice of move at round $k$ given previous moves

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- John gets $N \%$ of the cake (John's payoff)
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Best strategy for John is to split cake into half
It is not a "winning strategy" but it is an optimal strategy
It maximises his payoff

## Number of Player vs Number of Rounds

Number of players is not essential
It is important what the "goal" at each round is
Rounds with "same goal" mean played by "same player"

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It is important what the "goal" at each round is
Rounds with "same goal" mean played by "same player"
How to describe the goal at a particular round?
You could say: The goal is to win!
But maybe this is not possible (or might not even make sense) Instead, the goal should be described as:
a choice of outcome from each set of possible outcomes

As in...

# Q: How much would you like to pay for your flight? 



As in...

# Q: How much would you like to pay for your flight? <br> A: As little as possible! 



## Quantifiers

$R=$ set of outcomes
$X=$ set of possible moves

$$
\phi \in(X \rightarrow R) \rightarrow R
$$

describes the desired outcome $\phi p \in R$ given $p \in X \rightarrow R$

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describes the desired outcome $\phi p \in R$ given $p \in X \rightarrow R$
In the example:

$$
\begin{array}{ll}
R & =\text { prices (real numbers) } \\
X & =\text { possible flights } \\
X \rightarrow R & =\text { price of each flight } \\
\phi & =\text { minimal value functional }
\end{array}
$$

## Quantifiers

$$
\phi:(X \rightarrow R) \rightarrow R
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## Other Examples

| Operation | $\phi:$ | $(X \rightarrow R) \rightarrow R$ |  |
| :--- | ---: | :--- | ---: |
| Supremum | $\sup _{[0,1]}:$ | $([0,1] \rightarrow \mathbb{R}) \rightarrow \mathbb{R}$ |  |
| Integration | $\int_{0}^{1}$ | $:$ | $([0,1] \rightarrow \mathbb{R}) \rightarrow \mathbb{R}$ |
| Limit | $\lim$ | $:$ | $(\mathbb{N} \rightarrow R) \rightarrow R$ |
| Quantifiers | $\forall_{X}, \exists_{X}$ | $:$ | $(X \rightarrow \mathbb{B}) \rightarrow \mathbb{B}$ |
| Double negation | $\neg \neg X:$ | $(X \rightarrow \perp) \rightarrow \perp$ |  |
| Fixed point operator | fix $_{X}$ | $:$ | $(X \rightarrow X) \rightarrow X$ |

## Quantifiers

$$
\phi:(X \rightarrow R) \rightarrow R \quad\left(\equiv K_{R} X\right)
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Theorem (Maximum Value Theorem)
For any $p \in C[0,1]$ there is a point $a \in[0,1]$ such that

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## Theorem (Mean Value Theorem)

For any $p \in C[0,1]$ there is a point $a \in[0,1]$ such that

$$
\int_{0}^{1} p=p(a)
$$

## Theorem (Witness Theorem)

For any $p: X \rightarrow \mathbb{B}$ there is a point $a \in X$ such that

$$
\exists x^{X} p(x) \Leftrightarrow p(a)
$$

(similar to Hilbert's $\varepsilon$-term).

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## Theorem (Counter-example Theorem)

For any $p: X \rightarrow \mathbb{B}$ there is a point $a \in X$ such that

$$
\forall x^{X} p(x) \Leftrightarrow p(a)
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(a is counter-example to $p$ if one exists).

Let $J_{R} X \equiv(X \rightarrow R) \rightarrow X$

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Definition (Selection Functions)
$\varepsilon$ : $J_{R} X$ is called a selection function for $\phi: K_{R} X$ if

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\phi(p)=p(\varepsilon p)
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holds for all $p: X \rightarrow R$

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## Definition (Attainable Quantifiers)

A quantifier $\phi: K_{R} X$ is called attainable if it has a selection function $\varepsilon$ : $J_{R} X$

## For Instance

- $\sup : K_{\mathbb{R}}[0,1]$ is an attainable quantifier

$$
\sup (p)=p(\operatorname{argsup}(p))
$$

where argsup: $J_{\mathbb{R}}[0,1]$


## For Instance

- sup: $K_{\mathbb{R}}[0,1]$ is an attainable quantifier

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where argsup: $J_{\mathbb{R}}[0,1]$


- fix: $K_{X} X$ is an attainable quantifier

$$
\operatorname{fix}(p)=p(\operatorname{fix}(p))
$$

where fix: $J_{X} X\left(=K_{X} X\right)$

## Selection Functions and Quantifiers



Every selection function $\varepsilon: J_{R} X$ defines a quantifier $\bar{\varepsilon}$ : $K_{R} X$

$$
\bar{\varepsilon}(p)=p(\varepsilon(p))
$$

## Selection Functions and Quantifiers



Not all quantifiers are attainable, e.g. $R=\{0,1\}$

$$
\phi(p)=0
$$

## Selection Functions and Quantifiers



Different $\varepsilon$ might define same $\phi$, e.g. $X=[0,1]$ and $R=\mathbb{R}$

$$
\begin{aligned}
& \varepsilon_{0}(p)=\mu x \cdot \sup p=p(x) \\
& \varepsilon_{1}(p)=\nu x \cdot \sup p=p(x)
\end{aligned}
$$

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## Finite Sequential Games ( $n$ rounds)

Definition (A tuple $\left(R,\left(X_{i}\right)_{i<n},\left(\phi_{i}\right)_{i<n}, q\right)$ where)

- $R$ is the set of possible outcomes
- $X_{i}$ is the set of available moves at round $i$
- $\phi_{i}: K_{R} X_{i}$ is the goal quantifier for round $i$
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## Definition (Strategy)

Family of mappings

$$
\operatorname{next}_{k}: \prod_{i=0}^{k-1} X_{i} \rightarrow X_{k}
$$

## Definition (Strategic Play)

Given strategy next ${ }_{k}$ and partial play $\vec{a}=a_{0}, \ldots, a_{k-1}$, the strategic extension of $\vec{a}$ is $\mathbf{b}^{\vec{a}}=b_{k}^{\vec{a}}, \ldots, b_{n-1}^{\vec{a}}$ where

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Strategy next ${ }_{k}$ is optimal if for any partial play $\vec{a}$

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q\left(\vec{a}, \mathbf{b}^{\vec{a}}\right)=\phi_{k}\left(\lambda x_{k} \cdot q\left(\vec{a}, x_{k}, \mathbf{b}^{\vec{a}, x_{k}}\right)\right)
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A product of selection functions computes optimal strategies

## Standard Game Theory

When quantifiers are max or sup over finite or compact set
Then argsup exists (and hence sup is attainable)
Generalised Game $\mapsto$ Standard Game
Optimal strategy $\mapsto$ Strategy in Nash equilibrium
Product of argsup $\mapsto$ Backward induction!

## Fixed Point Theory

Fixed point operators are their own selection function
Generalised Game $\mapsto$ Operators on product space
Optimal strategy $\mapsto$ Bekiç's Lemma
Product of fix's $\mapsto$ The proof!

## Proof Theory

## Proof interpretation

$$
\exists i \leq n \forall x^{X_{i}} \exists r^{R} A_{i}(x, r) \quad \mapsto \quad \forall \varepsilon_{(\cdot)} \exists i \leq n \exists p A_{i}\left(\varepsilon_{i} p, p\left(\varepsilon_{i} p\right)\right)
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> Existence of optimal strategy actually implies the consistency of mathematics!

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- Infinite product $\Pi_{i} J_{R} X_{i} \rightarrow J_{R} \Pi_{i} X_{i}$ exists
(in some models)


## Summary

- Generalised notion of sequential game
- Generalised notion of optimal strategy (equilibrium)
- Product of sel. fct. computes optimal strategies
- Results from fixed point theory, topology, proof theory, etc, can be viewed as optimal strategies in certain games


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