Calculating Games with Higher-Order Functions

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(based on joint work with M. Escardó)

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Outline



Quantifiers and Selection Functions







Outline



Quantifiers and Selection Functions

3 Generalisation





- Early development in the 19th century
- Formal approach with von Neumann (1930's)



John von Neumann



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- Formal approach with von Neumann (1930's)
- n players
- n strategy sets X_1, \ldots, X_n
- payoff function $q \colon \vec{X} \to \mathbb{R}^n$



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John von Neumann

How should players choose their strategies in order to maximise their individual payoffs?



Calculating Games with Higher-Order Functions

Game Theory

Game Theory





Game Theory



Penalties

Two players

Strategy sets
$$X_1 = X_2 = \{L, R\}$$

Payoff function



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Strategy profile \vec{x} is in equilibrium if no player has an incentive to unilaterally change his strategy



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The "penalty" example shows that strategy profiles in equilibrium not necessarily exist either



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i.e. player chooses probability distribution on strategies

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Mixed strategies in equilibrium always exist



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Theorem (Nash)

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The "penalty" example is again an illustration of this: Players randomly choosing left or right is best they can do

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Simultaneous versus Sequential Games

- That's all in the case of simultaneous games
- With sequential games things are simpler and nicer
- Strategies: mappings from previous moves to current move

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• Similar definition of Nash equilibrium

Simultaneous versus Sequential Games

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But equilibrium always exists and can be computed by a technique called **backward induction**

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Backward Induction

 $q\colon X\times Y\times Z\to \mathbb{R}^3$



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Our Recent Work

1. Generalised notions of sequential game, Nash equilibrium and backward induction



Our Recent Work

- 1. Generalised notions of sequential game, Nash equilibrium and backward induction
- 2. Showed how general notions appear in topology, proof theory, and algorithms, amongst others





Outline



Quantifiers and Selection Functions







Single-player Games

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8		4		2	9	4		6
2	5	7	4	1	4		9	7
9			1	5	8		3	4
5	2	6	7	7		2	1	3
4		6		9		7		8
1	1	3	2	4 3	4 3	7		5
	9	2	3		4	5	3 7	6
3 7	6				1	3	2	1
3 7	1	4	7		9	4	3 7	2







Two-player Games

Two players: Black and White





Two-player Games

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Possible outcomes:

- Black wins
- White wins
- Draw





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Strategy: Choice of move at round k given previous moves





Two players: John and Julia



Another Game



Two players: John and Julia

John splits a cake. Julia chooses one of the two pieces



Another Game



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John splits a cake. Julia chooses one of the two pieces

Possible outcomes:

- John gets N% of the cake (John's payoff)
- Julia gets (100 N)% of the cake (Julia's payoff)



Another Game



Two players: John and Julia

John splits a cake. Julia chooses one of the two pieces

Possible outcomes:

- John gets N% of the cake (John's payoff)
- Julia gets (100 N)% of the cake (Julia's payoff)

Best strategy for John is to split cake into half

It is not a "winning strategy" but it is an **optimal strategy** It maximises his payoff

Number of Player vs Number of Rounds

Number of players is not essential

It is important what the "goal" at each round is

Rounds with "same goal" mean played by "same player"



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Rounds with "same goal" mean played by "same player"

How to describe the goal at a particular round?

You could say: The goal is to win!

But maybe this is not possible (or might not even make sense)

Instead, the goal should be described as:

a choice of outcome from each set of possible outcomes



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As in...

Q: How much would you like to pay for your flight?





As in...

Q: How much would you like to pay for your flight? A: As little as possible!




Quantifiers

- $R = \mathsf{set} \mathsf{ of outcomes}$
- X = set of possible moves

$$\phi \in (X \to R) \to R$$

describes the desired outcome $\phi p \in R$ given $p \in X \rightarrow R$



Quantifiers

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$$\phi \in (X \to R) \to R$$

describes the desired outcome $\phi p \in R$ given $p \in X \to R$ In the example:

- R = prices (real numbers)
- X = possible flights
- $X \rightarrow R = price of each flight$
- ϕ = minimal value functional



Calculating Games with Higher-Order Functions

Quantifiers and Selection Functions

Quantifiers

$$\phi : (X \to R) \to R$$



Quantifiers

$$\phi : (X \to R) \to R$$

Other Examples

Operation	ϕ	:	$(X \to R) \to R$
Supremum	$\sup_{[0,1]}$:	$([0,1] \to \mathbb{R}) \to \mathbb{R}$
Integration	\int_0^1	:	$([0,1] \to \mathbb{R}) \to \mathbb{R}$
Limit	lim	:	$(\mathbb{N} \to R) \to R$
Quantifiers	\forall_X, \exists_X	:	$(X \to \mathbb{B}) \to \mathbb{B}$
Double negation	$\neg \neg X$:	$(X \to \bot) \to \bot$
Fixed point operator	fix_X	:	$(X \to X) \to X$

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Quantifiers

$$\phi : (X \to R) \to R \qquad (\equiv K_R X)$$

Other Examples

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Theorem (Maximum Value Theorem)

For any $p \in C[0,1]$ there is a point $a \in [0,1]$ such that

 $\sup p = p(a)$



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Theorem (Mean Value Theorem)

For any $p \in C[0,1]$ there is a point $a \in [0,1]$ such that

$$\int_0^1 p = p(a)$$



Theorem (Witness Theorem)

For any $p: X \to \mathbb{B}$ there is a point $a \in X$ such that

$$\exists x^X p(x) \iff p(a)$$

(similar to Hilbert's ε -term).



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Theorem (Counter-example Theorem)

For any $p: X \to \mathbb{B}$ there is a point $a \in X$ such that

 $\forall x^X p(x) \iff p(a)$

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(a is counter-example to p if one exists).

Let $J_R X \equiv (X \to R) \to X$



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Definition (Selection Functions)

 ε : $J_R X$ is called a **selection function** for ϕ : $K_R X$ if

$$\phi(p) = p(\varepsilon p)$$

holds for all $p: X \to R$



Let
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Definition (Selection Functions)

 $\varepsilon \colon J_R X$ is called a **selection function** for $\phi \colon K_R X$ if

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holds for all $p: X \to R$

Definition (Attainable Quantifiers)

A quantifier ϕ : $K_R X$ is called **attainable** if it has a selection function ε : $J_R X$



For Instance

• sup:
$$K_{\mathbb{R}}[0, 1]$$
 is an attainable quantifier
 $\sup(p) = p(\operatorname{argsup}(p))$
where $\operatorname{argsup}: J_{\mathbb{R}}[0, 1]$





For Instance

• sup:
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where $\operatorname{argsup}: J_{\mathbb{R}}[0, 1]$

• fix: $K_X X$ is an attainable quantifier

$$\label{eq:fix} \begin{split} & \mathsf{fix}(p) = p(\mathsf{fix}(p)) \\ & \mathsf{where \ fix} \colon J_X X \ (= K_X X) \end{split}$$



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Selection Functions and Quantifiers



Every selection function $\varepsilon \colon J_R X$ defines a quantifier $\overline{\varepsilon} \colon K_R X$

$$\overline{\varepsilon}(p) = p(\varepsilon(p))$$

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Selection Functions and Quantifiers



Not all quantifiers are attainable, e.g. $R=\{0,1\}$

$$\phi(p) = 0$$

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Selection Functions and Quantifiers



Different ε might define same $\phi,$ e.g. X=[0,1] and $R=\mathbb{R}$

$$\varepsilon_0(p) = \mu x \cdot \sup p = p(x)$$

$$\varepsilon_1(p) = \nu x \cdot \sup p = p(x)$$

Outline



Quantifiers and Selection Functions







- Generalisation

Finite Sequential Games (n rounds)

Definition (A tuple $(R, (X_i)_{i < n}, (\phi_i)_{i < n}, q)$ where)

- R is the set of **possible outcomes**
- X_i is the set of **available moves** at round i
- $\phi_i : K_R X_i$ is the **goal quantifier** for round *i*
- $q: \prod_{i=0}^{n-1} X_i \to R$ is the outcome function

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Definition (Strategy)

Family of mappings

$$\operatorname{next}_k \colon \prod_{i=0}^{k-1} X_i \to X_k$$



Generalisation

Definition (Strategic Play)

Given strategy next_k and partial play $\vec{a} = a_0, \ldots, a_{k-1}$, the strategic extension of \vec{a} is $\mathbf{b}^{\vec{a}} = b_k^{\vec{a}}, \ldots, b_{n-1}^{\vec{a}}$ where

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Definition (Optimal Strategy)

Strategy next_k is **optimal** if for any partial play \vec{a}

$$q(\vec{a}, \mathbf{b}^{\vec{a}}) = \phi_k(\lambda x_k.q(\vec{a}, x_k, \mathbf{b}^{\vec{a}, x_k}))$$



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A product of selection functions computes optimal strategies

- Generalisation

Standard Game Theory

When quantifiers are \max or \sup over finite or compact set Then argsup exists (and hence \sup is attainable)

- ${\sf Generalised} \ {\sf Game} \quad \mapsto \quad {\sf Standard} \ {\sf Game}$
- ${\sf Optimal \ strategy} \quad \mapsto \quad {\sf Strategy \ in \ Nash \ equilibrium} \\$
- Product of $\operatorname{argsup} \mapsto \operatorname{Backward} \operatorname{induction!}$



- Generalisation

Fixed Point Theory

Fixed point operators are their own selection function

 ${\sf Generalised} \ {\sf Game} \quad \mapsto \quad {\sf Operators} \ {\sf on} \ {\sf product} \ {\sf space}$

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Optimal strategy \mapsto Bekiç's Lemma

Product of fix's \mapsto The proof!

Proof Theory

Proof interpretation

$$\exists i \leq n \forall x^{X_i} \exists r^R A_i(x, r) \quad \mapsto \quad \forall \varepsilon_{(\cdot)} \exists i \leq n \exists p A_i(\varepsilon_i p, p(\varepsilon_i p))$$



Proof Theory

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 $\varepsilon{}^{\prime}{\rm s}$ define quantifiers, which partially define a game

Computational interpretation relies on completing the definition of the game so optimal strategy solves problem



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Existence of optimal strategy actually implies the consistency of mathematics!



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3 Generalisation





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$$K_R X \times K_R Y \to K_R (X \times Y)$$

calculates optimal outcome



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• Infinite product $\Pi_i J_R X_i \to J_R \Pi_i X_i$ exists (in some models)



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Summary

- Generalised notion of sequential game
- Generalised notion of optimal strategy (equilibrium)
- Product of sel. fct. computes optimal strategies
- Results from fixed point theory, topology, proof theory, etc, can be viewed as optimal strategies in certain games

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