# A Finitisation of the Infinite Ramsey Theorem 

Paulo Oliva<br>Queen Mary University of London<br>(talk based on joint work with M. Escardó and T. Powell)

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## Outline

(1) Infinite Ramsey Theorem
(2) Backward Induction and Bar Recursion
(3) Infinite Pigeonhole Principle and Dependent Choice
(4) $€ 100$ Question

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exists an infinite set $S \subseteq \mathbb{N}$ where colouring is homogenous

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We shall witness equivalent "no-counterexample" variant

$$
\forall \varepsilon \exists x^{\mathbb{B}} \underbrace{\exists F^{\mathbb{N}^{\mathbb{N}}}}_{\text {approx }} \forall i \leq \varepsilon_{x} F \forall j<i(\underbrace{F j<F i}_{\text {large }} \wedge \underbrace{c(F j, F i)=x}_{\text {monochromatic }})
$$

where $\varepsilon_{x}:(\mathbb{N} \rightarrow \mathbb{N}) \rightarrow \mathbb{N}$

## The Erdős/Radu Tree

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- Define a colouring $c^{\prime}: \mathbb{N} \rightarrow \mathbb{B}$ as $c^{\prime}(i)=c(\alpha(i), \alpha(i+1))$
- By IPP $c^{\prime}$ has an infinite monochromatic set $p$
- Hence, $\alpha \circ p$ is a monochromatic set for $c$


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## (1) Infinite Ramsey Theorem

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## Nash Equilibrium - Backward Induction

Three players, payoff function $q: X \times Y \times Z \rightarrow \mathbb{R}^{3}$
Each player is trying to maximise their own payoff


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Let $\operatorname{argmax}_{i}:\left(X_{i} \rightarrow \mathbb{R}^{n}\right) \rightarrow X_{i}$ find a point $x \in X_{i}$ at which the function $p: X_{i} \rightarrow \mathbb{R}^{n}$ has maximal $i$-value

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For $q: \Pi_{j=i}^{n-1} X_{j} \rightarrow \mathbb{R}^{n}$, define

$$
\operatorname{BI}_{i}^{n-1}(q) \stackrel{\Pi_{j=i}^{n-1} X_{j}}{=} \begin{cases}{[]} & \text { if } i=n \\ c_{i} * \operatorname{BI}_{i+1}^{n-1}\left(q_{c_{i}}\right) & \text { otherwise }\end{cases}
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where $c_{i}=\operatorname{argmax}_{i}\left(\lambda x \cdot q_{x}\left(\operatorname{BI}_{i+1}^{n}\left(q_{x}\right)\right)\right)$

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where $c_{i}=\operatorname{argmax}_{i}\left(\lambda x \cdot q_{x}\left(\mathrm{BI}_{i+1}^{n}\left(q_{x}\right)\right)\right)$
Each player's optimal strategy can be described as

$$
\operatorname{next}_{i}(s)=\operatorname{argmax}_{i}(\underbrace{\lambda x \cdot q_{s * x}\left(\mathrm{Bl}_{i+1}^{n}\left(q_{s * x}\right)\right)}_{p: X \rightarrow \mathbb{R}^{n}})
$$

## Spector's Bar Recursion

Let

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s: X^{*} \quad \omega: X^{\mathbb{N}} \rightarrow \mathbb{N} \quad q: X^{*} \rightarrow R \quad \varepsilon_{s}: J_{R} X
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Given $s, \omega$ and $\varepsilon_{s}$ define

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\operatorname{EPS}_{s}^{\omega}(\varepsilon)(q) \stackrel{X^{*}}{=} \begin{cases}{[]} & \text { if } \omega(\hat{s})<|s| \\ c * \operatorname{EPS}_{s * c}^{\omega}(\varepsilon)\left(q_{c}\right) & \text { otherwise }\end{cases}
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Using product $\otimes$ of selection functions

$$
\operatorname{EPS}_{s}^{\omega}(\varepsilon) \stackrel{J_{R} X^{*}}{=} \begin{cases}\lambda q \cdot[] & \text { if } \omega(\hat{s})<|s| \\ \varepsilon_{s} \otimes \lambda x \cdot \operatorname{EPS}_{s * x}^{\omega}(\varepsilon) & \text { otherwise }\end{cases}
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## Main Theorem

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We have that
(1) there exist $p_{i}: X \rightarrow R$, for $i<|s|$, such that

$$
\begin{array}{rll}
s_{i} & \stackrel{X}{=} \varepsilon_{i} p_{i} \\
q s & \stackrel{R}{=} p_{i}\left(\varepsilon_{i} p_{i}\right)
\end{array}
$$

(2) $\omega \hat{s}<|s|$

## Computational Interpretation

Main theorem gives straightforward interpretations:

$$
\begin{array}{lll}
\Sigma_{1}^{0} \text {-comprehension } & \mapsto & \text { EPS for } \varepsilon: J_{\mathbb{N}} \mathbb{N} \\
\text { WKL } & \mapsto & \text { EPS for } \varepsilon: J_{\mathbb{N}} \mathbb{B} \\
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Three nested calculations of optimal strategies

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## Infinite Pigeonhole Principle IPP

Let $\mathbf{n}=\{0,1, \ldots, n-1\}$
Given a colouring $c: \mathbb{N} \rightarrow \mathbf{n}$ the principle IPP says

$$
\exists k<n \underbrace{\exists p^{\mathbb{N} \rightarrow \mathbb{N}}}_{\text {subsequence }} \forall i(\underbrace{p i \geq i}_{\text {unbounded }} \wedge \underbrace{c(p i)=k}_{\text {homogeneous }})
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We look at its no-counterexample interpretation

$$
\forall \varepsilon \exists k<n \exists p^{\mathbb{N} \rightarrow \mathbb{N}}\left(p\left(\varepsilon_{k} p\right) \geq \varepsilon_{k} p \wedge c\left(p\left(\varepsilon_{k} p\right)\right)=k\right)
$$

where $k$ and $p$ only need to be "good" at point $\varepsilon_{k} p$

Question: How to witness $k$ and $p$ given $c$ and $\varepsilon$ ?

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Let

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\begin{aligned}
s & =\mathrm{EPS}_{i=0}^{n-1}\left(\varepsilon_{i}\right)(\max ) \\
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Hence, for $k$ and $p$ as above,

$$
p\left(\varepsilon_{k} p\right) \geq \varepsilon_{k} p \quad c\left(p\left(\varepsilon_{k} p\right)\right)=k
$$

## Dependent Choice

Consider this version of $\Pi_{1}$-dependent choice

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Its ND-interpretation would be

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\exists \varepsilon \forall s, p A_{s}\left(\varepsilon_{s} p, p\left(\varepsilon_{s} p\right)\right) \rightarrow \forall \omega, q \exists \alpha A_{[\alpha](\omega \alpha)}(\alpha(\omega \alpha), q \alpha)
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$$

To witness $\alpha$ given $\varepsilon, \omega, q$ simply take

$$
\begin{aligned}
\alpha & =\operatorname{EPS}_{[]}^{\omega}\left(\varepsilon_{i}\right)(q) \\
s & =[\alpha](\omega \alpha) \\
p & =p_{s}
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## Spector'62 first defines general bar recursion:

6.2. Bar recursion. For ease in reading we omit showing $G, H, Y$ as arguments of $\phi$.

$$
\phi(x, C)=\left\{\begin{array}{l}
G(x,\langle C 0, \cdots, C(x-1)\rangle) \text { if } Y(\langle C 0, \cdots, C(x-1)\rangle)<x \\
H\left[\lambda a \phi\left(x^{\prime},\langle C 0, \cdots, C(x-1), a\rangle, x,\langle C 0, \cdots, C(x-1)\rangle\right]\right. \text { otherwise. }
\end{array}\right.
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Thus $\phi(x, C)$ is defined outright if $Y(\langle C 0, \cdots, C(x-1)\rangle)<x$, and in terms of $\lambda a \phi\left(x^{\prime},\langle C 0, \cdots, C(x-1), a\rangle\right)$ otherwise.

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## But only uses restricted bar recursion:

10. The interpretation of $\mathbf{F}$ is provable in $\Sigma_{4}$. This is the only point where we make use of bar recursion, and we use it in the following restricted form, where the parameter $G_{0}$ is not exhibited as an argument of $\phi$ for greater readability.
$\mathrm{BR} \quad \phi z C x= \begin{cases}C x & \text { if } x<z, \\ 0 & \text { if } x \geqq z \wedge Y(\langle C 0, \cdots, C(z-1)\rangle)<z, \\ \phi\left(z^{\prime},\left\langle C 0, \cdots, C(z-1), a_{0}\right\rangle, x\right) \quad \text { otherwise },\end{cases}$
where

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a_{0}=G_{0}\left(z, \lambda a \phi\left(z^{\prime},\langle C 0, \cdots, C(z-1), a\rangle\right),\right.
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and by convention, $\phi(z, C)=\lambda x \phi(z, C, x)$.

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## $€ 100$ Question: Quantifiers vs Selection Functions

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whereas restricted form is iterated prod. of selection funct.

$$
\operatorname{EPS}_{s}^{\omega}(\varepsilon) \stackrel{J_{R} X^{*}}{=} \begin{cases}\lambda q \cdot[] & \text { if } \omega(\hat{s})<1 \\ \varepsilon_{s} \otimes^{s} \lambda x . \operatorname{EPS}_{s * x}^{\omega}(\varepsilon) & \text { otherwise }\end{cases}
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\phi_{s}:(X \rightarrow R) \rightarrow R \quad \varepsilon_{s}:(X \rightarrow R) \rightarrow X
$$

Spector general form is iterated product of quantifiers

$$
\mathrm{EPQ}_{s}^{\omega}(\phi) \stackrel{K_{R} X^{*}}{=} \begin{cases}\lambda q \cdot q([]) & \text { if } \omega(\hat{s})<|s| \\ \phi_{s} \otimes^{\mathrm{a}} \lambda x \cdot \mathrm{EPQ}_{s * x}^{\omega}(\phi) & \text { otherwise }\end{cases}
$$

whereas restricted form is iterated prod. of selection funct.

$$
\operatorname{EPS}_{s}^{\omega}(\varepsilon) \stackrel{J_{R} X^{*}}{=} \begin{cases}\lambda q \cdot[] & \text { if } \omega(\hat{s})<1 \\ \varepsilon_{s} \otimes^{s} \lambda x . \operatorname{EPS}_{s * x}^{\omega}(\varepsilon) & \text { otherwise }\end{cases}
$$

Q: EPS is T-definable in EPQ, how about the converse?

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